

SOFT-THRESHOLDING AND L1 REGULARIZATION

1/2

For strictly convex functions, there exists only one unique minimum and for convex functions a stationary point (if it exists) is a minimum.

We now separately investigate z_j for $\theta_j > 0$ and $\theta_j < 0$.

NB: on these halflines z_j is differentiable (with possible stationary point) since

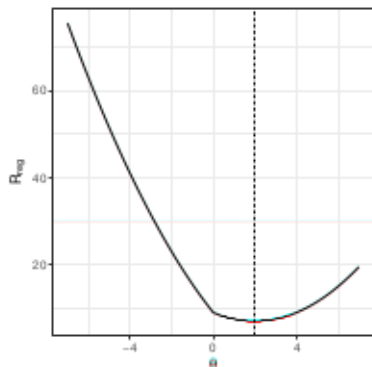
- for $\theta_j > 0$: $\frac{d}{d\theta_j} |\theta_j| = \frac{d}{d\theta_j} \theta_j = 1$,
- for $\theta_j < 0$: $\frac{d}{d\theta_j} |\theta_j| = \frac{d}{d\theta_j} (-\theta_j) = -1$.



SOFT-THRESHOLDING AND L1 REGULARIZATION

/ 3

1) $\theta_j > 0$:



$$\frac{d}{d\theta_j} z_j(\theta_j) = H_{j,j}\theta_j - H_{j,j}\hat{\theta}_j + \lambda \stackrel{!}{=} 0$$

$$\Rightarrow \hat{\theta}_{\text{lasso},j} = \hat{\theta}_j - \frac{\lambda}{H_{j,j}} > 0$$

This minimum is only valid if $\hat{\theta}_{\text{lasso},j} > 0$ and so it must hold that

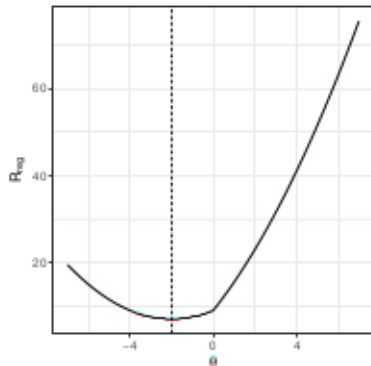
$$\hat{\theta}_j > \frac{\lambda}{H_{j,j}}$$



SOFT-THRESHOLDING AND L1 REGULARIZATION

1 / 4

2) $\hat{\theta}_{\text{lasso},j} < 0$:



$$\frac{d}{d\theta_j} z_j(\theta_j) = H_{j,j}\theta_j - H_{j,j}\hat{\theta}_j - \lambda \stackrel{!}{=} 0$$

$$\Rightarrow \hat{\theta}_{\text{lasso},j} = \hat{\theta}_j + \frac{\lambda}{H_{j,j}} < 0$$

This minimum is only valid if $\hat{\theta}_{\text{lasso},j} < 0$ and so it must hold that

$$\hat{\theta}_j < -\frac{\lambda}{H_{j,j}}$$



