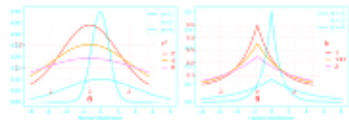


Introduction to Machine Learning

Regularization

Bayesian Priors



Learning goals

- RRM is same as MAP in Bayes
- Gaussian/Laplace prior corresponds to L_2/L_1 penalty

RRM VS. BAYES / 2

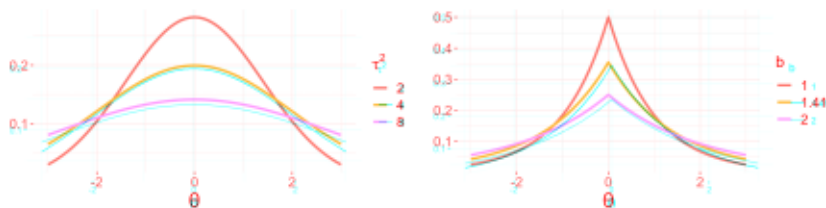
The maximum a posteriori (MAP) estimator of θ is now the minimizer of

$$-\log p(y | \theta, \mathbf{x}) - \log q(\theta).$$

- Again, we identify the loss $L(y, f(\mathbf{x} | \theta))$ with $-\log(p(y|\theta, \mathbf{x}))$.
- If $q(\theta)$ is constant (i.e., we used a uniform, non-informative prior), the second term is irrelevant and we arrive at ERM.
- If not, we can identify $J(\theta) \propto -\log(q(\theta))$, i.e., the log-prior corresponds to the regularizer, and the additional λ , which controls the strength of our penalty, usually influences the peakedness / inverse variance / strength of our prior.



RRM VS. BAYES / 3



- L_2 regularization corresponds to a zero-mean Gaussian prior with constant variance on our parameters: $\theta_j \sim \mathcal{N}(0, \tau^2)$
- L_1 corresponds to a zero-mean Laplace prior: $\theta_j \sim \text{Laplace}(0, b)$. $\text{Laplace}(\mu, b)$ has density $\frac{1}{2b} \exp(-\frac{|\mu-x|}{b})$, with scale parameter b , mean μ and variance $2b^2$.
- In both cases, regularization strength increases as variance of prior decreases: more prior mass concentrated around 0 encourages shrinkage.
- Elastic-net regularization corresponds to a compromise between Gaussian and Laplacian priors [▶ Zou and Hastie 2005](#) [▶ Hans 2011](#)

