



## FORWARD STAGewise ADDITIVE MODELING / 2

### Why is gradient boosting a good choice for this problem?

- Because of the additive structure it is difficult to jointly minimize  $\mathcal{R}_{\text{emp}}(f)$  w.r.t.  $((\alpha^{[1]}, \theta^{[1]}), \dots, (\alpha^{[M]}, \theta^{[M]}))$ , which is a very high-dimensional parameter space (though this is less of a problem nowadays, especially in the case of numeric parameter spaces).
- Considering trees as base learners is worse as we would have to grow  $M$  trees in parallel so they work optimally together as an ensemble.
- Stagewise additive modeling has nice properties, which we want to make use of, e.g. for regularization, early stopping, ...



## FORWARD STAGewise ADDITIVE MODELING / 3

Hence, we add additive components in a greedy fashion by sequentially minimizing the risk only w.r.t. the next additive component:

$$\min_{\alpha, \theta} \sum_{i=1}^n L \left( y^{(i)}, \hat{f}^{[m-1]}(\mathbf{x}^{(i)}) + \alpha b(\mathbf{x}^{(i)}, \theta) \right)$$



Doing this iteratively is called **forward stagewise additive modeling**.

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### Algorithm Forward Stagewise Additive Modeling.

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- 1: Initialize  $\hat{f}^{[0]}(\mathbf{x})$  with loss optimal constant model
  - 2: **for**  $m = 1 \rightarrow M$  **do**
  - 3:  $(\hat{\alpha}^{[m]}, \hat{\theta}^{[m]}) = \arg \min_{\alpha, \theta} \sum_{i=1}^n L \left( y^{(i)}, \hat{f}^{[m-1]}(\mathbf{x}^{(i)}) + \alpha b(\mathbf{x}^{(i)}, \theta) \right)$
  - 4: Update  $\hat{f}^{[m]}(\mathbf{x}) \leftarrow \hat{f}^{[m-1]}(\mathbf{x}) + \hat{\alpha}^{[m]} b(\mathbf{x}, \hat{\theta}^{[m]})$
  - 5: **end for**
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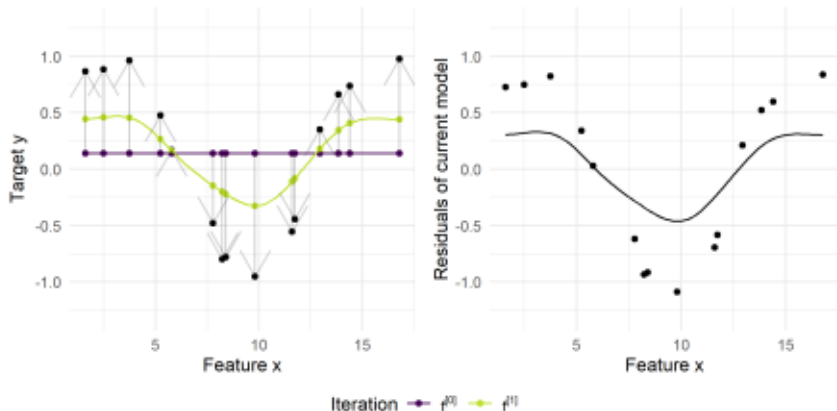




# GRADIENT BOOSTING / 4

**In a nutshell:** One boosting iteration is exactly one approximated gradient descent step in function space, which minimizes the empirical risk as much as possible.

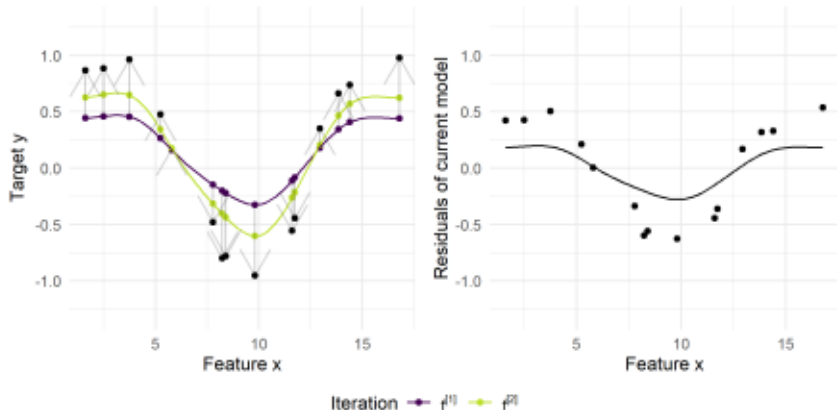
**Iteration 1:**



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Instead of moving the function values for each observation by a fraction closer to the observed data, we fit a regression base learner to the pseudo-residuals (right plot).

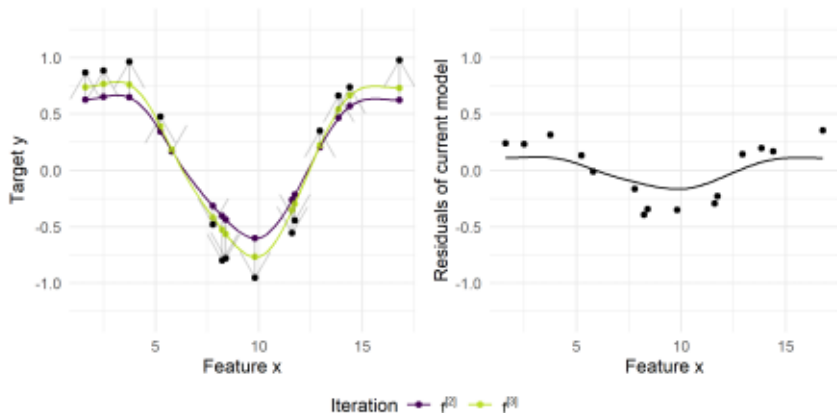
Iteration 2:



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This base learner is then added to the current state of the ensemble weighted by the learning rate (here:  $\alpha = 0.4$ ) and for the next iteration again the pseudo-residuals of the adapted ensemble are calculated and a base learner is fitted to them.

**Iteration 3:**





# GRADIENT BOOSTING ALGORITHM

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## Algorithm Gradient Boosting Algorithm.

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- 1: Initialize  $\hat{f}^{[0]}(\mathbf{x}) = \arg \min_{\theta_0 \in \mathbb{R}} \sum_{i=1}^n L(y^{(i)}, \theta_0)$
  - 2: **for**  $m = 1 \rightarrow M$  **do**
  - 3:   For all  $i$ :  $\tilde{r}^{[m](i)} = - \left[ \frac{\partial L(y, f)}{\partial f} \right]_{f=\hat{f}^{[m-1]}(\mathbf{x}^{(i)}, y=y^{(i)}}$
  - 4:   Fit a regression base learner to the vector of pseudo-residuals  $\tilde{r}^{[m]}$ :
  - 5:    $\hat{\theta}^{[m]} = \arg \min_{\theta} \sum_{i=1}^n (\tilde{r}^{[m](i)} - b(\mathbf{x}^{(i)}, \theta))^2$
  - 6:   Set  $\alpha^{[m]}$  to  $\alpha$  being a small constant value or via line search
  - 7:   Update  $\hat{f}^{[m]}(\mathbf{x}) = \hat{f}^{[m-1]}(\mathbf{x}) + \alpha^{[m]} b(\mathbf{x}, \hat{\theta}^{[m]})$
  - 8: **end for**
  - 9: Output  $\hat{f}(\mathbf{x}) = \hat{f}^{[M]}(\mathbf{x})$
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Note that we also initialize the model in a loss-optimal manner.

## LINE SEARCH

The learning rate in gradient boosting influences how fast the algorithm converges. Although a small constant learning rate is commonly used in practice, it can also be replaced by a line search.



Line search is an iterative approach to find a local minimum. In the case of setting the learning rate, the following one-dimensional optimization problem has to be solved:

$$\hat{\alpha}^{[m]} = \underset{\alpha}{\operatorname{arg\,min}} \sum_{i=1}^m \mathcal{L}(y^{(i)}, f^{[m-1]}(\mathbf{x}) + \alpha b(\mathbf{x}, \hat{\theta}^{[m]}))$$

Optionally, an (inexact) backtracking line search can be used to find the  $\alpha^{[m]}$  that minimizes the above equation.