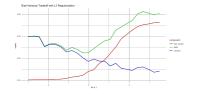
# **Introduction to Machine Learning**

Regularization
Perspectives on Ridge Regression
(Deep-Dive)





#### Learning goals

- Interpretation of L2 regularization as row-augmentation
- Interpretation of L2 regularization as minimizing risk under feature noise

# PERSPECTIVES ON L2 REGULARIZATION

We already saw two interpretations of *L*2 regularization.

• We know that it is equivalent to a constrained optimization problem:

$$\hat{\theta}_{\text{ridge}} = \underset{\boldsymbol{\theta}}{\arg\min} \sum_{i=1}^{n} \left( \boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{T} \mathbf{x}^{(i)} \right)^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2} = (\mathbf{X}^{T} \mathbf{X} + \lambda \boldsymbol{I})^{-1} \mathbf{X}^{T} \mathbf{y}$$

For some t depending on  $\lambda$  this is equivalent to:

$$\hat{\theta}_{\text{ridge}} = \underset{\boldsymbol{\theta}}{\text{arg min}} \sum_{i=1}^{n} \left( y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 \text{ s.t. } \|\boldsymbol{\theta}\|_2^2 \leq t$$

• Bayesian interpretation of ridge regression: For additive Gaussian errors  $\mathcal{N}(0,\sigma^2)$  and i.i.d. normal priors  $\theta_j \sim \mathcal{N}(0,\tau^2)$ , the resulting MAP estimate is  $\hat{\theta}_{\text{ridge}}$  with  $\lambda = \frac{\sigma^2}{\tau^2}$ :

$$\hat{\theta}_{\mathsf{MAP}} = \operatorname*{arg\,max}_{\theta} \log[p(\mathbf{y}|\mathbf{X}, \boldsymbol{\theta})p(\boldsymbol{\theta})] = \operatorname*{arg\,min}_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(y^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)}\right)^{2} + \frac{\sigma^{2}}{\tau^{2}} \|\boldsymbol{\theta}\|_{2}^{2}$$



## L2 AND ROW-AUGMENTATION

We can also recover the ridge estimator by performing least-squares on a **row-augmented** data set: Let  $\tilde{\mathbf{X}} := \begin{pmatrix} \mathbf{X} \\ \sqrt{\lambda} \mathbf{I}_p \end{pmatrix}$  and  $\tilde{\mathbf{y}} := \begin{pmatrix} \mathbf{y} \\ \mathbf{0}_p \end{pmatrix}$ .

With the augmented data, the unreg. least-squares solution  $\hat{\theta}$  is:

$$\tilde{\boldsymbol{\theta}} = \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n+p} \left( \boldsymbol{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2$$

$$= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left( \boldsymbol{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 + \sum_{j=1}^{p} \left( 0 - \sqrt{\lambda} \theta_j \right)^2$$

$$= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left( \boldsymbol{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 + \lambda \|\boldsymbol{\theta}\|_2^2$$

 $\Longrightarrow \hat{ heta}_{\mathsf{ridge}}$  is the least-squares solution  $ilde{ heta}$  but using  $ilde{\mathbf{X}}, ilde{\mathbf{y}}$  instead of  $\mathbf{X}, \mathbf{y}!$ 

This is a sometimes useful "recasting" or "rewriting" for ridge.



## **L2 AND NOISY FEATURES**

Now consider perturbed features  $\tilde{x}^{(i)} := \mathbf{x}^{(i)} + \delta^{(i)}$  where  $\delta^{(i)} \stackrel{\textit{iid}}{\sim} (\mathbf{0}, \lambda \mathbf{I}_p)$ . We assume no specific distribution. Now minimize risk with L2 loss, we define it slightly different than usual, as here our data  $\mathbf{x}^{(i)}$ ,  $y^{(i)}$  are fixed, but we integrate over the random permutations  $\delta$ :

$$\begin{split} \mathcal{R}(\boldsymbol{\theta}) &:= \mathbb{E}_{\boldsymbol{\delta}} \Big[ \sum_{i=1}^n (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top \tilde{\boldsymbol{x}}^{(i)})^2 \Big] = \mathbb{E}_{\boldsymbol{\delta}} \Big[ \sum_{i=1}^n (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top (\boldsymbol{x}^{(i)} + \boldsymbol{\delta}^{(i)}))^2 \Big] \ \Big| \ \text{expand} \\ \mathcal{R}(\boldsymbol{\theta}) &= \mathbb{E}_{\boldsymbol{\delta}} \Big[ \sum_{i=1}^n ((\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top \boldsymbol{x}^{(i)})^2 - 2\boldsymbol{\theta}^\top \boldsymbol{\delta}^{(i)} (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top \boldsymbol{x}^{(i)}) + \boldsymbol{\theta}^\top \boldsymbol{\delta}^{(i)} \boldsymbol{\delta}^{(i)\top} \boldsymbol{\theta}) \Big] \end{split}$$

By linearity of expectation, 
$$\mathbb{E}_{\delta}[\delta^{(i)}] = \mathbf{0}_{\rho}$$
 and  $\mathbb{E}_{\delta}[\delta^{(i)}\delta^{(i)\top}] = \lambda \mathbf{I}_{\rho}$ , this is

$$\mathcal{R}(\boldsymbol{\theta}) = \sum_{i=1}^{n} ((\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)})^{2} - 2\boldsymbol{\theta}^{\top} \mathbb{E}_{\boldsymbol{\delta}} [\boldsymbol{\delta}^{(i)}] (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)}) + \boldsymbol{\theta}^{\top} \mathbb{E}_{\boldsymbol{\delta}} [\boldsymbol{\delta}^{(i)} \boldsymbol{\delta}^{(i)\top}] \boldsymbol{\theta})$$
$$= \sum_{i=1}^{n} (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)})^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2}$$

 $\implies$  Ridge regression on unperturbed features  $\mathbf{x}^{(i)}$  turns out to be the same as minimizing squared loss averaged over feature noise distribution!