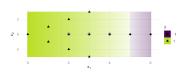
## Introduction to Machine Learning

# Nonlinear Support Vector Machines The Kernel Trick

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#### Learning goals

- Know how to efficiently introduce non-linearity via the kernel trick
- Know common kernel functions (linear, polynomial, radial)
- Know how to compute predictions of the kernel SVM

## DUAL SVM PROBLEM WITH FEATURE MAP

The dual (soft-margin) SVM is:

$$\begin{aligned} \max_{\alpha} \quad & \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_{i} \alpha_{j} y^{(i)} y^{(j)} \left\langle \phi \left( \mathbf{x}^{(i)} \right), \phi \left( \mathbf{x}^{(j)} \right) \right\rangle \\ \text{s.t.} \quad & 0 \le \alpha_{i} \le C, \\ & \sum_{i=1}^{n} \alpha_{i} y^{(i)} = \mathbf{0}, \end{aligned}$$

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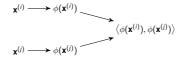
Here we replaced all features  $\mathbf{x}^{(i)}$  with feature-generated, transformed versions  $\phi(\mathbf{x}^{(i)})$ .

We see: The optimization problem only depends on **pair-wise inner products** of the inputs.

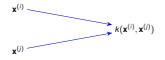
This now allows a trick to enable efficient solving.

## KERNEL = FEATURE MAP + INNER PRODUCT

Instead of first mapping the features to the higher-dimensional space and calculating the inner products afterwards,



it would be nice to have an efficient "shortcut" computation:



We will see: Kernels give us such a "shortcut".

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### **MERCER KERNEL**

**Definition:** A (Mercer) kernel on a space  $\mathcal{X}$  is a continuous function

$$k: \mathcal{X} \times \mathcal{X} \to \mathbb{R}$$

of two arguments with the properties

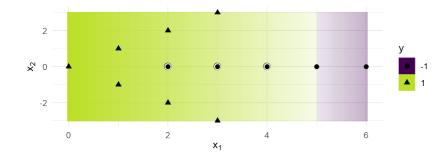
- Symmetry:  $k(\mathbf{x}, \mathbf{\tilde{x}}) = k(\mathbf{\tilde{x}}, \mathbf{x})$  for all  $\mathbf{x}, \mathbf{\tilde{x}} \in \mathcal{X}$ .
- Positive definiteness: For each finite subset {x<sup>(1)</sup>,..., x<sup>(n)</sup>} the kernel Gram matrix K ∈ ℝ<sup>n×n</sup> with entries K<sub>ij</sub> = k(x<sup>(i)</sup>, x<sup>(j)</sup>) is positive semi-definite.

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## **CONSTANT AND LINEAR KERNEL**

- Every constant function taking a non-negative value is a (very boring) kernel.
- An inner product is a kernel. We call the standard inner product k(x, x̃) = x<sup>⊤</sup>x̃ the linear kernel. This is simply our usual linear SVM as discussed.

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## SUM AND PRODUCT KERNELS

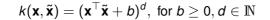
A kernel can be constructed from other kernels  $k_1$  and  $k_2$ :

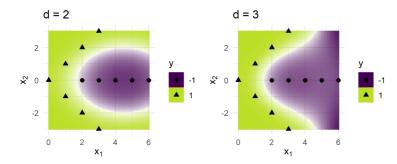
- For  $\lambda \geq 0$ ,  $\lambda \cdot k_1$  is a kernel.
- $k_1 + k_2$  is a kernel.
- $k_1 \cdot k_2$  is a kernel (thus also  $k_1^n$ ).

The proofs remain as (simple) exercises.

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#### **POLYNOMIAL KERNEL**







From the sum-product rules it directly follows that this is a kernel.

#### **RBF KERNEL**

The "radial" Gaussian kernel is defined as

$$k(\mathbf{x}, \tilde{\mathbf{x}}) = \exp(-\frac{\|\mathbf{x} - \tilde{\mathbf{x}}\|^2}{2\sigma^2})$$

 $k(\mathbf{x}, \tilde{\mathbf{x}}) = \exp(-\gamma \|\mathbf{x} - \tilde{\mathbf{x}}\|^2), \ \gamma > 0$ 

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1.25 1.00 1.00 ĩ 2 -0.75 v ×  $r = ||\mathbf{x} - \widetilde{\mathbf{x}}||^2$ × 0 − -1 0.50 . 0.25 0.25 --2 0.00 0.00 0 2 0.5 1.0 1.5 2.0 -4 ò 4 **x**<sub>1</sub> **X**1 r

or

## **KERNEL SVM**

We kernelize the dual (soft-margin) SVM problem by replacing all inner products  $\langle \phi(\mathbf{x}^{(i)}), \phi(\mathbf{x}^{(j)}) \rangle$  by kernels  $k(\mathbf{x}^{(i)}, \mathbf{x}^{(j)})$ 

$$\begin{aligned} \max_{\alpha} \quad & \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_{i} \alpha_{j} y^{(i)} y^{(j)} \left\langle \phi \left( \mathbf{x}^{(i)} \right), \phi \left( \mathbf{x}^{(j)} \right) \right\rangle \\ \text{s.t.} \quad & 0 \leq \alpha_{i} \leq C, \\ & \sum_{i=1}^{n} \alpha_{i} y^{(i)} = 0. \end{aligned}$$

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This problem is still convex because *K* is psd!

## KERNEL SVM

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$$\max_{\alpha} \sum_{i=1}^{n} \alpha_{i} - \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} \alpha_{i} \alpha_{j} y^{(i)} y^{(j)} k(\mathbf{x}^{(i)}, \mathbf{x}^{(j)})$$
  
s.t.  $0 \le \alpha_{i} \le C$ ,  
 $\sum_{i=1}^{n} \alpha_{i} y^{(i)} = 0.$ 

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## KERNEL SVM

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In more compact matrix notation, with *K* denoting the kernel matrix:

$$\max_{\alpha \in \mathbb{R}^n} \quad \mathbf{1}^\top \alpha - \frac{1}{2} \alpha^\top \operatorname{diag}(\mathbf{y}) \mathbf{K} \operatorname{diag}(\mathbf{y}) \alpha$$
s.t.  $\alpha^\top \mathbf{y} = \mathbf{0},$   
 $\mathbf{0} \le \alpha \le \mathbf{C}.$ 

This problem is still convex because *K* is psd!

### **KERNEL SVM: PREDICTIONS**

For the linear soft-margin SVM we had:

$$f(\mathbf{x}) = \hat{\theta}^T \mathbf{x} + \theta_0$$
 and  $\hat{\theta} = \sum_{i=1}^n \alpha_i y^{(i)} \mathbf{x}^{(i)}$ 

After the feature map this becomes:

$$f(\mathbf{x}) = \left\langle \hat{\theta}, \phi(\mathbf{x}) \right\rangle + \theta_0$$
 and  $\hat{\theta} = \sum_{i=1}^n \alpha_i y^{(i)} \phi(\mathbf{x}^{(i)})$ 

Assuming that the dot-product still follows its bi-linear rules in the mapped space and using the kernel trick again:

$$\left\langle \hat{\theta}, \phi(\mathbf{x}) \right\rangle = \left\langle \sum_{i=1}^{n} \alpha_{i} y^{(i)} \phi(\mathbf{x}^{(i)}), \phi(\mathbf{x}) \right\rangle = \sum_{i=1}^{n} \alpha_{i} y^{(i)} \left\langle \phi(\mathbf{x}^{(i)}), \phi(\mathbf{x}) \right\rangle =$$
$$= \sum_{i=1}^{n} \alpha_{i} y^{(i)} k(\mathbf{x}^{(i)}, \mathbf{x}), \quad \text{so:} \quad f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_{i} y^{(i)} k(\mathbf{x}^{(i)}, \mathbf{x}) + \theta_{0}$$



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## MNIST EXAMPLE

- Through this kernelization we can now conveniently perform feature generation even for higher-dimensional data. Actually, this is how we computed all previous examples, too.
- $\bullet\,$  We again consider MNIST with 28  $\times$  28 bitmaps of gray values.
- A polynomial kernel extracts  $\binom{d+p}{d} 1$  features and for the RBF kernel the dimensionality would be infinite.
- We train SVMs again on 700 observations of the MNIST data set and use the rest of the data for testing; and use C=1.

000000000000000000000000000000000000000		
222222222222 3333333333333333333		Error
4414444444444 5555555555555555555555555	linear	0.134
666 <b>66666666666</b> 7771 <b>7</b> 7777777777777	poly $(d = 2)$	0.119
8888888888888888888888 999999999999999	RBF (gamma = 0.001)	0.12
() () / / / / () () () / / /	RBF (gamma = 1)	0.184

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## **FINAL COMMENTS**

- The kernel trick allows us to make linear machines non-linear in a very efficient manner.
- Linear separation in high-dimensional spaces is very flexible.
- Learning takes place in the feature space, while predictions are computed in the input space.
- Both the polynomial and Gaussian kernels can be computed in linear time. Computing inner products of features is **much faster** than computing the features themselves.
- What if a good feature map  $\phi$  is already available? Then this feature map canonically induces a kernel by defining  $k(\mathbf{x}, \tilde{\mathbf{x}}) = \langle \phi(\mathbf{x}), \phi(\tilde{\mathbf{x}}) \rangle$ . There is no problem with an explicit feature representation as long as it is efficiently computable.

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