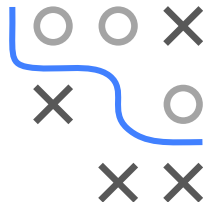


Optimization in Machine Learning

First order methods

Gradient descent



Learning goals

- Iterative Descent / Line Search
- Descent directions
- GD
- ERM with GD
- Pseudoresiduals

ITERATIVE DESCENT

Let f be the height of a mountain depending on the geographic coordinates (x_1, x_2)

$$f : \mathbb{R}^2 \rightarrow \mathbb{R}, \quad f(x_1, x_2) = y.$$

Goal: Reach the valley

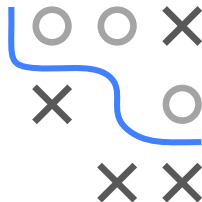
$$\arg \min_{\mathbf{x}} f(\mathbf{x})$$

Central idea: Repeat

- 1 At current location $\mathbf{x} \in \mathbb{R}^d$ search for **descent direction** $\mathbf{d} \in \mathbb{R}^d$
- 2 Move along \mathbf{d} until f „sufficiently“ reduces (**step size control**) and update location



"Walking down the hill, towards the valley."

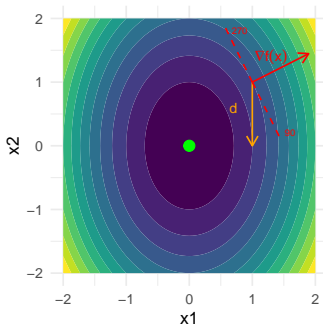
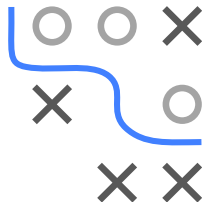


ITERATIVE DESCENT

Let $f : \mathbb{R}^d \rightarrow \mathbb{R}$ continuously differentiable.

Definition: $\mathbf{d} \in \mathbb{R}^d$ is a **descent direction** in \mathbf{x} if

$$D_{\mathbf{d}}f(\mathbf{x}) = \nabla f(\mathbf{x})^T \mathbf{d} < 0 \text{ (neg. directional derivative)}$$



Angle between $\nabla f(\mathbf{x})$ and \mathbf{d} must be $\in (90^\circ, 270^\circ)$.

ITERATIVE DESCENT / 2

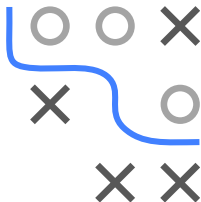
Algorithm Iterative Descent / Line search

- 1: Starting point $\mathbf{x}^{[0]} \in \mathbb{R}^d$
 - 2: **while** Stopping criterion not met **do**
 - 3: Calculate a descent direction $\mathbf{d}^{[t]}$ for current $\mathbf{x}^{[t]}$
 - 4: Find $\alpha^{[t]}$ s.t. $f(\mathbf{x}^{[t+1]}) < f(\mathbf{x}^{[t]})$ for $\mathbf{x}^{[t+1]} = \mathbf{x}^{[t]} + \alpha^{[t]}\mathbf{d}^{[t]}$.
 - 5: Update $\mathbf{x}^{[t+1]} = \mathbf{x}^{[t]} + \alpha^{[t]}\mathbf{d}^{[t]}$
 - 6: **end while**
-

NB: Terminology is sometimes ambiguous: "line search" can refer to Step 4 (selecting the step size that decreases $f(\mathbf{x})$) and can mean umbrella term for iterative descent algorithms.

Key questions:

- How to choose $\mathbf{d}^{[t]}$ (now)
- How to choose $\alpha^{[t]}$ (later)

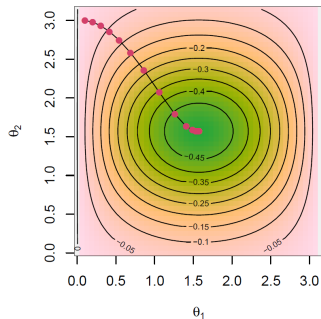
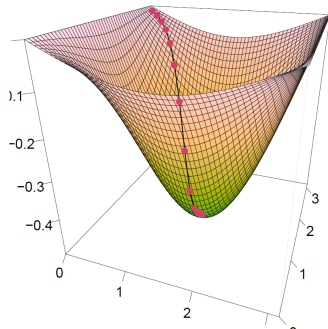
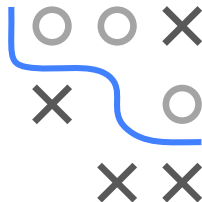


GRADIENT DESCENT

Properties of gradient:

- $\nabla f(\mathbf{x})$: direction of greatest increase
- $-\nabla f(\mathbf{x})$: direction of greatest decrease

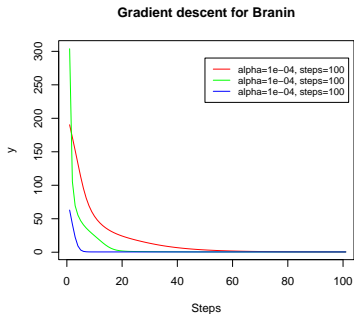
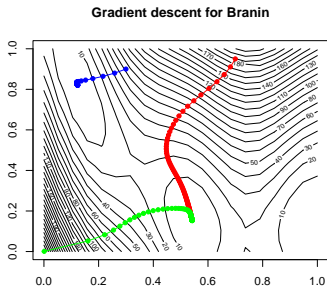
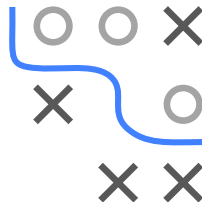
Using $\mathbf{d} = -\nabla f(\mathbf{x})$ is called **gradient descent**.



GD for $f(x_1, x_2) = -\sin(x_1) \cdot \frac{1}{2\pi} \exp((x_2 - \pi/2)^2)$ with sensibly chosen step size $\alpha^{[t]}$.

GD AND MULTIMODAL FUNCTIONS

Outcome will depend on start point.



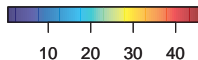
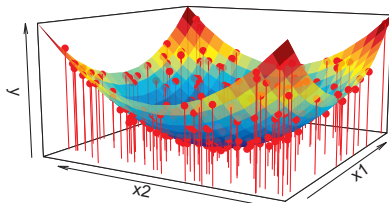
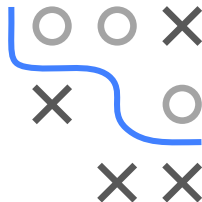
100 iters of GD with const $\alpha = 10^{-4}$.

ERM FOR NN WITH GD

Let $\mathcal{D} = ((\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(n)}, y^{(n)}))$, with $y = x_1^2 + x_2^2$ and minimize

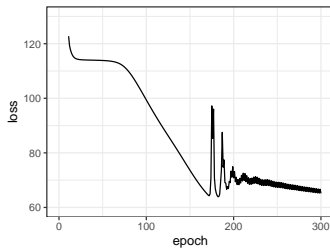
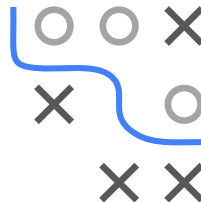
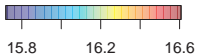
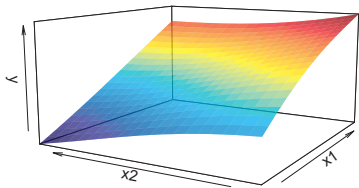
$$\mathcal{R}_{\text{emp}}(\boldsymbol{\theta}) = \sum_{i=1}^n \left(f(\mathbf{x} \mid \boldsymbol{\theta}) - y^{(i)} \right)^2$$

where $f(\mathbf{x} \mid \boldsymbol{\theta})$ is a neural network with 2 hidden layers (2 units each).



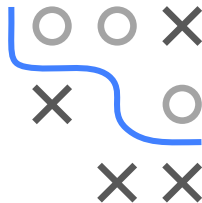
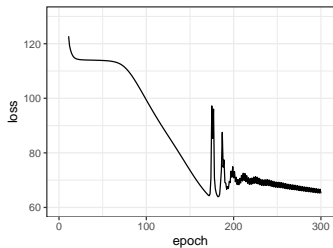
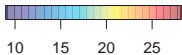
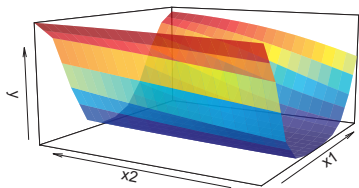
ERM FOR NN WITH GD / 2

After 10 iters of GD:



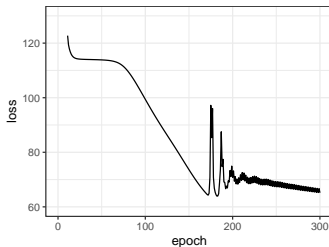
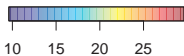
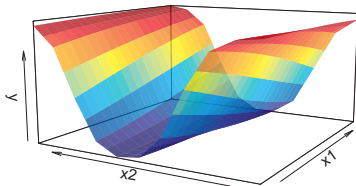
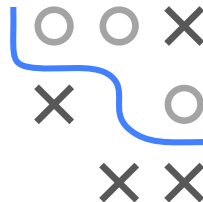
ERM FOR NN WITH GD / 3

After 100 iters of GD:



ERM FOR NN WITH GD / 4

After 300 iters of GD (note the zig-zag-behavior after iter. 200):



GD FOR ERM: PSEUDORESIDUALS

Gradient for ERM problem:

$$-\frac{\partial \mathcal{R}_{\text{emp}}(\theta)}{\partial \theta} = -\frac{\partial \sum_{i=1}^n L(y^{(i)}, f(\mathbf{x}^{(i)} | \theta))}{\partial \theta} = -\sum_{i=1}^n \underbrace{\frac{\partial L(y^{(i)}, f(\mathbf{x}^{(i)}))}{\partial f}}_{\text{pseudo residual } \tilde{r}^{(i)}(f)} \frac{\partial f(\mathbf{x}^{(i)} | \theta)}{\partial \theta}$$

- **pseudo residuals** tell us how to distort $f(\mathbf{x}^{(i)})$ to achieve greatest decrease of $L(y^{(i)}, f(\mathbf{x}^{(i)}))$ (best pointwise update)
- $\frac{\partial f(\mathbf{x}^{(i)} | \theta)}{\partial \theta}$ tells us how to modify θ accordingly and wiggle model output
- GD step sums up these modifications across all observations i

NB: Pseudo-residuals $\tilde{r}(f)$ match usual residuals for L2 loss:

$$\begin{aligned} \frac{\partial L(y, f(\mathbf{x}))}{\partial f} &= \frac{1}{2} \frac{\partial (y - f)^2}{\partial f} \Big|_{f=f(\mathbf{x})} \\ &= y - f(\mathbf{x}) \end{aligned}$$

