# Interpretable Machine Learning

# **Conditional Feature Importance (CFI)**



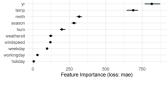


Figure: Bike Sharing Dataset

#### Learning goals

- Extrapolation and Conditional Sampling
- Conditional Feature Importance (CFI)
- Interpretation of CFI and difference to PFI

• **Permutation Feature Importance Idea:** Replace the feat. of interest  $x_j$  with an indep. sample from the marginal dist.  $\mathbb{P}(x_j)$ , e.g. by randomly perm. obs. in  $x_j$ 



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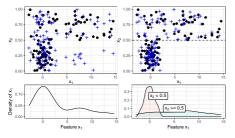


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- Conditional Feature Importance Idea: Resample  $x_j$  from the cond. dist.  $\mathbb{P}(x_j|x_{-j})$ , s.t. the joint dist. is preserved, i.e.,  $\mathbb{P}(x_j|x_{-j})\mathbb{P}(x_{-j}) = \mathbb{P}(x_j, x_{-j})$



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Example: Conditional permutation scheme Molnar et. al (2020)



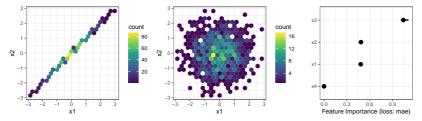
- $X_2 \sim U(0, 1)$  and  $X_1 \sim N(0, 1)$  if  $X_2 < 0.5$ , else  $X_1 \sim N(4, 4)$  (black dots)
- Left: For X<sub>2</sub> < 0.5, permuting X<sub>1</sub> (crosses) preserves marginal (but not joint) distribution
  - $\rightsquigarrow$  Bottom: Marginal density of  $X_1$
- **Right:** Permuting X₁ within subgroups X₂ < 0.5 & X₂ ≥ 0.5 reduces extrapolation
  - $\rightsquigarrow$  Bottom: Density of  $X_1$  conditional

on groups



# **RECALL: EXTRAPOLATION IN PFI**

**Example:** Let  $y = x_3 + \epsilon_y$  with  $\epsilon_y \sim N(0, 0.1)$  where  $x_1 := \epsilon_1, x_2 := x_1 + \epsilon_2$  are highly correlated ( $\epsilon_1 \sim N(0, 1), \epsilon_2 \sim N(0, 0.01)$ ) and  $x_3 := \epsilon_3, x_4 := \epsilon_4$ , with  $\epsilon_3, \epsilon_4 \sim N(0, 1)$ . All noise terms are independent. Fitting a LM yields  $\hat{f}(\mathbf{x}) \approx 0.3x_1 - 0.3x_2 + x_3$ .



Hexbin plot of  $x_1, x_2$  before permuting  $x_1$  (left), after permuting  $x_1$  (center), and PFI scores (right)  $\Rightarrow x_1$  and  $x_2$  should be irrelevant for the prediction  $\hat{f}(\mathbf{x})$  for

 $\{\mathbf{x}:\mathbb{P}(\mathbf{x})>0\}$  as  $0.3x_1-0.3x_2pprox 0$ 

 $\Rightarrow$  PFI evaluates model on unrealistic obs. outside  $\mathbb{P}(\mathbf{x}) \rightsquigarrow x_1$  and  $x_2$  are considered relevant



# CONDITIONAL FEATURE IMPORTANCE Strobl et al. (2008)

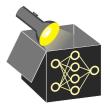
▶ Hooker et al. (2021)

Conditional feature importance (CFI) for features  $x_S$  using test data  $\mathcal{D}$ :

- Measure the error with unperturbed features.
- Measure the error with perturbed feature values  $\tilde{x}^{S|-S}$ , where  $\tilde{x}_{S}^{S|-S} \sim \mathbb{P}(x_{S}|x_{-S})$
- Repeat permuting the feature (e.g., *m* times) and average the difference of both errors:

$$\widehat{\textit{CFI}}_{S} = \tfrac{1}{m} \sum_{k=1}^{m} \mathcal{R}_{emp}(\hat{f}, \tilde{\mathcal{D}}_{(k)}^{S|-S}) - \mathcal{R}_{emp}(\hat{f}, \mathcal{D})$$

Here,  $\tilde{D}^{S|-S}$  denotes the dataset where features  $x_S$  where sampled conditional on the remaining features  $x_{-S}$ .



### IMPLICATIONS OF CFI ( König et al. (2020)

**Interpretation:** Due to the conditional sampling w.r.t. all other features, CFI quantifies a feature's unique contribution to the model performance.

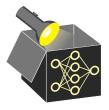


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### Entanglement with data:

- If feature  $x_S$  does not contribute unique information about y, i.e.,  $x_S \perp \!\!\!\perp y | x_{-S} \Rightarrow$ CFI = 0
- Why? Under the conditional independence P(x̃<sup>S|-S</sup>, y) = P(x, y)
   → no prediction-relevant information is destroyed by permutation of x<sub>S</sub> conditional on x<sub>-S</sub>



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### Entanglement with model:

- $\bullet~$  If the model does not use a feature  $\Rightarrow CFI = 0$
- Why? Then the prediction is not affected by any perturbation of the feature ~> model performance does not change after conditional permutation



# **IMPLICATIONS OF CFI**

Can we gain insight into whether ...

- the feature  $x_j$  is causal for the prediction?
  - $CFI_j \neq 0 \Rightarrow$  model relies on  $x_j$  (converse does not hold, see next slide)



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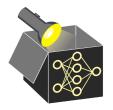
- the feature  $x_j$  is causal for the prediction?
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- 2 the variable  $x_j$  contains prediction-relevant information?
  - If  $x_j \not\perp y$  but  $x_j \perp y | x_{-j}$  (e.g.,  $x_j$  and  $x_{-j}$  share information)  $\Rightarrow CFI_j = 0$
  - *x<sub>j</sub>* is not exploited by model (regardless of whether it is useful for *y* or not)
     ⇒ *CFI<sub>j</sub>* = 0



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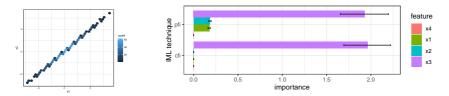
Can we gain insight into whether ...

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  - $CFl_j \neq 0 \Rightarrow$  model relies on  $x_j$  (converse does not hold, see next slide)
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  - If  $x_j \not\perp y$  but  $x_j \perp y | x_{-j}$  (e.g.,  $x_j$  and  $x_{-j}$  share information)  $\Rightarrow CFI_j = 0$
  - $x_j$  is not exploited by model (regardless of whether it is useful for y or not)  $\Rightarrow CFl_j = 0$
- **③** Does the model require access to  $x_j$  to achieve its prediction performance?
  - $CFl_j \neq 0 \Rightarrow x_j$  contributes unique information (meaning  $x_j \not\perp y | x_{-j}$ )
  - Only uncovers the relationships that were exploited by the model



# **COMPARISON: PFI AND CFI**

**Example:** Let  $y = x_3 + \epsilon_y$  with  $\epsilon_Y \sim N(0, 0.1)$  where  $x_1 := \epsilon_1, x_2 := x_1 + \epsilon_2$  are highly correlated ( $\epsilon_1 \sim N(0, 1), \epsilon_2 \sim N(0, 0.01)$ ) and  $x_3 := \epsilon_3, x_4 := \epsilon_4$ , with  $\epsilon_3, \epsilon_4 \sim N(0, 1)$ . All noise terms are independent. Fitting a LM yields  $\hat{f}(\mathbf{x}) \approx 0.3x_1 - 0.3x_2 + x_3$ .





**Figure:** Density plot for  $x_1$ ,  $x_2$  before permuting  $x_1$  (left). PFI and CFI (right).

 $\Rightarrow x_1$  and  $x_2$  are irrelevant for the prediction  $\hat{f}(\mathbf{x})$  for  $\{\mathbf{x} : \mathbb{P}(\mathbf{x}) > 0\}$  as

 $0.3x_1 - 0.3x_2 \approx 0$ 

 $\Rightarrow$  PFI evaluates model on unrealistic obs. outside  $\mathbb{P}(\mathbf{x}) \rightsquigarrow x_1, x_2$  are considered relevant (PFI > 0)

 $\Rightarrow$  Since  $x_1$  can be reconstructed from  $x_2$  and vice versa, CFI considers  $x_1$  and  $x_2$  to be irrelevant