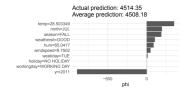
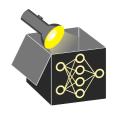
# **Interpretable Machine Learning**

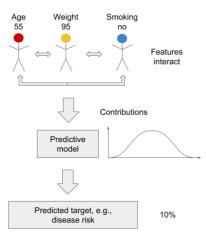
# **Shapley Values for Local Explanations**



#### Learning goals

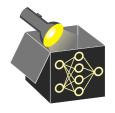
- See model predictions as a cooperative game
- Transfer the Shapley value concept from game theory to machine learning







• Game: Make prediction  $\hat{f}(x_1, x_2, \dots, x_p)$  for a single observation **x** 



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- Players: Features x<sub>j</sub>, j ∈ {1,...,p} which cooperate to produce a prediction
   → How can we make a prediction with a subset of features without changing the model?
  - $\leadsto$  PD function:  $\hat{f}_{S}(\mathbf{x}_{S}):=\int_{X_{-S}}\hat{f}(\mathbf{x}_{S},X_{-S})d\mathbb{P}_{X_{-S}}$  ("removing" by marginalizing over -S)



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- Value function / payout of coalition  $S \subseteq P$  for observation **x**:

$$v(S) = \hat{\mathit{f}}_{S}(\mathbf{x}_{S}) - \mathbb{E}_{\mathbf{x}}(\hat{\mathit{f}}(\mathbf{x})), \text{ where } \hat{\mathit{f}}_{S} : \mathcal{X}_{S} \mapsto \mathcal{Y}$$

 $\rightarrow$  subtraction of  $\mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$  ensures that  $\nu$  is a value function with  $\nu(\emptyset) = 0$ 

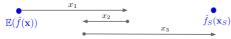
$$\mathbb{E}(\hat{f}(\mathbf{x})) \qquad \qquad x_1 \qquad \qquad \hat{f}_S(\mathbf{x}_S)$$



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ightharpoonup subtraction of  $\mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$  ensures that v is a value function with  $v(\emptyset)=0$ 

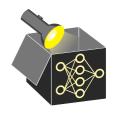


• Marginal contribution:  $v(S \cup \{j\}) - v(S) = \hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) - \hat{f}_{S}(\mathbf{x}_{S})$  $\rightarrow \mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$  cancels out due to the subtraction of value functions



Shapley value  $\phi_i$  of feature *j* for observation **x** via **order definition**:

$$\phi_j(\mathbf{x}) = \frac{1}{|P|!} \sum_{\tau \in \Pi} \hat{f}_{S_j^{\tau} \cup \{j\}}(\mathbf{x}_{S_j^{\tau} \cup \{j\}}) - \hat{f}_{S_j^{\tau}}(\mathbf{x}_{S_j^{\tau}})$$
marginal contribution of feature  $j$ 



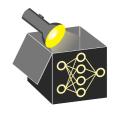
- Interpretation: Feature  $x_i$  contributed  $\phi_i$  to difference between  $\hat{f}(\mathbf{x})$  and average prediction
  - → Note: Marginal contributions and Shapley values can be negative
- For exact computation of  $\phi_i(\mathbf{x})$ , the PD function  $\hat{f}_S(\mathbf{x}_S) = \frac{1}{n} \sum_{i=1}^n \hat{f}(\mathbf{x}_S, \mathbf{x}_{-S}^{(i)})$  for any set of features S can be used which yields

$$\phi_j(\mathbf{x}) = \frac{1}{|P|! \cdot n} \sum_{\tau \in \Pi} \sum_{i=1}^n \hat{f}(\mathbf{x}_{S_j^{\tau} \cup \{j\}}, \mathbf{x}_{-\{S_j^{\tau} \cup \{j\}\}}^{(i)}) - \hat{f}(\mathbf{x}_{S_j^{\tau}}, \mathbf{x}_{-S_j^{\tau}}^{(i)})$$

 $\rightarrow$  Note:  $\hat{f}_S$  marginalizes over all other features -S using all observations  $i=1,\ldots,n$ 

 Exact Shapley value computation is problematic for high-dimensional feature spaces

 $\leadsto$  For 10 features, there are already |P|!= 10!  $\approx$  3.6 million possible orders of features



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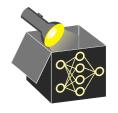
Estimation of  $\phi_i$  for observation **x** of model  $\hat{t}$  fitted on data  $\mathcal{D}$  using sample size M:

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$$\mathbf{x}$$
 with  $\mathbf{z}^{(m)}$ :

•  $\mathbf{x}_{+j}^{(m)} = (\underbrace{X_{\tau^{(1)}}, \dots, X_{\tau^{(|S_m|-1)}}, X_j}_{\mathbf{x}_{S_m \cup \{j\}}}, \underbrace{Z_{\tau^{(|S_m|+1)}}^{(m)}, \dots, Z_{\tau^{(p)}}^{(m)}}_{\mathbf{z}_{-\{S_m \cup \{j\}\}}})$  takes features

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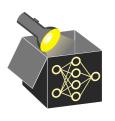
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 $S_m$  from **x** 

Compute difference 
$$\phi_j^m = \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)})$$
 $\leadsto \hat{f}_{S_m}(\mathbf{x}_{S_m})$  is approximated by  $\hat{f}(\mathbf{x}_{-j}^{(m)})$  and  $\hat{f}_{S_m \cup \{j\}}(\mathbf{x}_{S_m \cup \{j\}})$  by  $\hat{f}(\mathbf{x}_{+j}^{(m)})$  over  $M$  iters.



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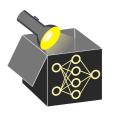
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 $S_m$  from **x** 

- **6** Compute difference  $\phi_i^m = \hat{f}(\mathbf{x}_{+i}^{(m)}) \hat{f}(\mathbf{x}_{-i}^{(m)})$  $\rightsquigarrow \hat{f}_{S_m}(\mathbf{x}_{S_m})$  is approximated by  $\hat{f}(\mathbf{x}_{-i}^{(m)})$  and  $\hat{f}_{S_m \cup \{i\}}(\mathbf{x}_{S_m \cup \{i\}})$  by  $\hat{f}(\mathbf{x}_{+i}^{(m)})$ over M iters.
- 2 Compute Shapley value  $\phi_i = \frac{1}{M} \sum_{m=1}^{M} \phi_i^m$



## SHAPLEY VALUE APPROXIMATION - ILLUSTRATION

Definition

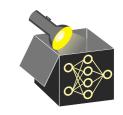
x: obs. of interest

 $\mathbf{x}$  with feature values in  $S_m$  (other are replaced)

$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{m=1}^{M} \left[ \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)}) \right]$$

 $\mathbf{x}$  with feature values in  $S_m \cup \{j\}$ 

	Temperature	Humidity	Windspeed	Year
$\boldsymbol{x}$	10.66	56	11	2012
$x_{+j}$	10.66	56	$random: z_{windspeed}^{(m)}$	2012
$x_{-j}$	10.66	56	$random: z_{windspeed}^{(m)}$	$random: z_{year}^{(m)}$
			,	•
				7



### **SHAPLEY VALUE APPROXIMATION - ILLUSTRATION**

#### **Definition**

Contribution of feature 
$$j$$
 to coalition  $S_m$  
$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{m=1}^{M} \left[ \hat{f}(\mathbf{x}_{+j}{}^{(m)}) - \hat{f}(\mathbf{x}_{-j}{}^{(m)}) \right]$$
$$:= \Delta(j, S_m)$$



- $\Delta(j, S_m) = \hat{f}(\mathbf{x}_{+j}^{(m)}) \hat{f}(\mathbf{x}_{-j}^{(m)})$  is the marginal contribution of feature j to coalition  $S_m$
- Here: Feature *year* contributes +700 bike rentals if it joins coalition  $S_m = \{temp, hum\}$

	Temperature	Humidity	Windspeed	Year	Count	
$\boldsymbol{x}$	10.66	56	11	2012		
$x_{+j}$	10.66	56	$random: z_{windspeed}^{(m)}$	2012	5600	700
$x_{-j}$	10.66	56	$random: z_{windspeed}^{(m)}$	$random: z_{year}^{(m)}$	4900	700
			`	•	$\stackrel{}{\frown}$	$\Delta(j,S_m)$
				${\mathcal J}$	f	marginal contribution

## **SHAPLEY VALUE APPROXIMATION - ILLUSTRATION**

#### **Definition**

$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{j=1}^{M} \left[ \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)}) \right]$$



- Compute marginal contribution of feature j towards the prediction across all randomly drawn feature coalitions  $S_1, \ldots, S_m$
- Average all *M* marginal contributions of feature *j*
- Shapley value  $\phi_j$  is the payout of feature j, i.e., how much feature year contributed to the overall prediction in bicycle counts of a specific observation  $\mathbf{x}$

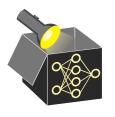
$$m=1$$
 2 M  $300$   $\Delta(j,S_m)$ 



We take the general axioms for Shapley Values and apply it to predictions:

• Efficiency: Shapley values add up to the (centered) prediction:

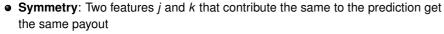
$$\sum_{j=1}^{p} \phi_j = \hat{f}(\mathbf{x}) - \mathbb{E}_{\mathbf{x}}(\hat{f}(X))$$



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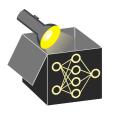
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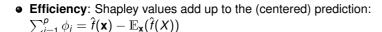


→ interaction effects between features are fairly divided

$$\hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) = \hat{f}_{S \cup \{k\}}(\mathbf{x}_{S \cup \{k\}})$$
 for all  $S \subseteq P \setminus \{j, k\}$  then  $\phi_j = \phi_k$ 



We take the general axioms for Shapley Values and apply it to predictions:





- **Symmetry**: Two features *j* and *k* that contribute the same to the prediction get the same payout
  - → interaction effects between features are fairly divided

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 Dummy / Null Player: Shapley value of a feature that does not influence the prediction is zero → if a feature was not selected by the model (e.g., tree or LASSO), its Shapley value is zero

$$\hat{f}_{S\cup\{j\}}(\mathbf{x}_{S\cup\{j\}})=\hat{f}_S(\mathbf{x}_S)$$
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We take the general axioms for Shapley Values and apply it to predictions:

• **Efficiency**: Shapley values add up to the (centered) prediction:

$$\sum_{j=1}^{p} \phi_j = \hat{f}(\mathbf{x}) - \mathbb{E}_{\mathbf{x}}(\hat{f}(X))$$

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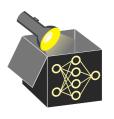
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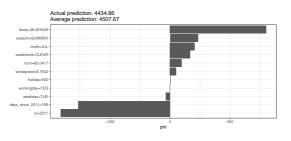
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• Additivity: For a prediction with combined payouts, the payout is the sum of payouts:  $\phi_j(v_1) + \phi_j(v_2) \leadsto$  Shapley values for model ensembles can be combined



### **BIKE SHARING DATASET**





- Shapley values of observation i = 200 from the bike sharing data
- Difference between model prediction of this observation and the average prediction of the data is fairly distributed among the features (i.e.,  $4434-4507\approx-73$ )
- Feature value temp = 28.5 has the most positive effect, with a contribution (increase of prediction) of about +400

### **ADVANTAGES AND DISADVANTAGES**

#### Advantages:

- Solid theoretical foundation in game theory
- Prediction is fairly distributed among the feature values → easy to interpret for a user
- Contrastive explanations that compare the prediction with the average prediction

#### Disadvantages:

- Without sampling, Shapley values need a lot of computing time to inspect all possible coalitions
- Like many other IML methods, Shapley values suffer from the inclusion of unrealistic data observations when features are correlated

