## **Introduction to Machine Learning**

# Evaluation Training Error





#### Learning goals

- Understand the definition of training error
- Understand why train error is unreliable for models of higher complexity when overfitting can occur

### **TRAINING ERROR**

Simply plugin predictions for data that model has been trained on:

$$ho(\mathbf{y}_{ ext{train}}, \mathbf{F}_{ ext{train}})$$
 where  $\mathbf{F}_{ ext{train}} = egin{bmatrix} \hat{t}_{\mathcal{D}_{ ext{train}}}(\mathbf{x}_{ ext{train}}^{(1)}) \ \dots \ \hat{t}_{\mathcal{D}_{ ext{train}}}(\mathbf{x}_{ ext{train}}^{(m)}) \end{bmatrix}$ 



A.k.a. apparent error or resubstitution error.

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### EXAMPLE 1: KNN

For large data, and some models, train error **can maybe** yield a good approximation of the GE:

- Use *k*-NN (*k* = 15).
- Up to 30K points from spirals to train.
- Use very large extra set for testing (to measure "true GE").





We increase train size, and see how gap between train error and GE closes.



### EXAMPLE 1: KNN / 2

- Fix train size to 500 and vary k.
- Low train error for small *k* is deceptive. Model is very local and overfits.





k = 2; trainerr = 0.08, testerr = 0.14



#### Black region are misclassifications from large test test.

### **EXAMPLE 2: POLYNOMIAL REGRESSION**

Sample data from  $0.5 + 0.4 \cdot \sin(2\pi x) + \epsilon$ 





We fit a *d*<sup>th</sup>-degree polynomial:

$$f(\mathbf{x} \mid \boldsymbol{\theta}) = \theta_0 + \theta_1 \mathbf{x} + \dots + \theta_d \mathbf{x}^d = \sum_{j=0}^d \theta_j \mathbf{x}^j.$$

### EXAMPLE 2: POLYNOMIAL REGRESSION / 2

Simple model selection problem: Which d?

Visual inspection vs quantitative MSE on training set:

0.50

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- d = 1: MSE = 0.036: clearly underfitting
- d = 3: MSE = 0.003: pretty OK
- *d* = 9: MSE = 0.001: clearly overfitting

Using the train error chooses overfitting model of maximal complexity.

0.75

1.00

0.25 -

0.00 -

0.00

0.25

### **TRAIN ERROR CAN EASILY BECOME 0**

- For 1-NN it is always 0 as each  $\mathbf{x}^{(i)}$  is its own NN at test time.
- Extend any ML training in the following way: After normal fitting, we also store the training data. During prediction, we first check whether *x* is already stored in this set. If so, we replicate its label. The train error of such an (unreasonable) procedure will be 0.
- There are so called interpolators interpolating splines, interpolating Gaussian processes - whose predictions can always perfectly match the regression targets, they are not necessarily good as they will interpolate noise, too.

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### **CLASSICAL STATISTICAL GOF MEASURES**

- **Goodness-of-fit** measures like *R*<sup>2</sup>, likelihood, AIC, BIC, deviance are all based on the training error.
- For models of restricted capacity, and enough data, and non-violated distributional assumptions: they might work.
- Hard to gauge when that breaks, for high-dim, more complex data.
- How do you compare to non-param ML-like models?

Out-of-sample testing is probably always a good idea!

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