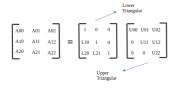
Algorithms and Data Structures

Matrix Decomposition Gaussian Elimination (LU Decomposition)





Learning goals

- Gaussian elimination (LU decomposition)
- Properties of LU decomposition

Aim: Solve LES of the form $\mathbf{A}\mathbf{x} = \mathbf{b}$

with $\mathbf{A} \in \mathbb{R}^{n \times n}$ regular (invertible), $\mathbf{x} \in \mathbb{R}^n$ and $\mathbf{b} \in \mathbb{R}^n$.

Calculate A = LU (or PA = LU), where L is a normalized lower triangular matrix, U is an upper triangular matrix, and P is a permutation matrix.

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & \cdots & 0 \\ I_{21} & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ I_{n1} & \cdots & I_{n(n-1)} & 1 \end{pmatrix} \cdot \begin{pmatrix} u_{11} & \cdots & \cdots & u_{1n} \\ 0 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & u_{nn} \end{pmatrix}$$

- 2 Solve Ly(=L(Ux)=Ax)=b.
- Solve Ux = y.



Let $\mathbf{A}\mathbf{x} = \mathbf{b}$ be a LES

$$\begin{pmatrix} 2 & 8 & 1 \\ 4 & 4 & -1 \\ -1 & 2 & 12 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 32 \\ 16 \\ 52 \end{pmatrix}$$



 \bullet A = LU

To convert **A** into an upper triangular matrix, we need 3 elementary transformations of type III:

$$\begin{pmatrix} 2 & 8 & 1 \\ 4 & 4 & -1 \\ -1 & 2 & 12 \end{pmatrix} \quad Z_2 - 2Z_1 \qquad \rightarrow \quad \begin{pmatrix} 2 & 8 & 1 \\ 0 & -12 & -3 \\ 0 & 6 & \frac{25}{2} \end{pmatrix} \quad Z_3 + \frac{1}{2}Z_2$$

$$\rightarrow \quad \begin{pmatrix} 2 & 8 & 1 \\ 0 & -12 & -3 \\ 0 & 0 & 11 \end{pmatrix} = \mathbf{U}.$$

If we write these transformations in matrix notation, we obtain

$$\mathbf{T}_{3}\mathbf{T}_{2}\mathbf{T}_{1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & \frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \frac{1}{2} & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -\frac{1}{2} & \frac{1}{2} & 1 \end{pmatrix}$$

Hence,

$$\mathbf{T}_{3}\mathbf{T}_{2}\mathbf{T}_{1}\mathbf{A} = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -\frac{1}{2} & \frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} 2 & 8 & 1 \\ 4 & 4 & -1 \\ -1 & 2 & 12 \end{pmatrix} = \begin{pmatrix} 2 & 8 & 1 \\ 0 & -12 & -3 \\ 0 & 0 & 11 \end{pmatrix} = \mathbf{U}$$

and

$$\bm{A} = \bm{T}_1^{-1} \bm{T}_2^{-1} \bm{T}_3^{-1} \bm{U} = \bm{L} \bm{U}$$

with

$$\boldsymbol{L} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -\frac{1}{2} & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{1}{2} & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -\frac{1}{2} & -\frac{1}{2} & 1 \end{pmatrix}.$$



General Theory:

The so-called Frobenius matrix

$$\mathsf{T}_k = \mathsf{I} - \mathsf{c}_k \mathsf{e}_k^{ op}$$

with

$$\mathbf{c}_{k} = \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ \mu_{k+1} \\ \vdots \\ \mu_{n} \end{pmatrix}, \quad \mathbf{e}_{k} = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \quad \mathbf{T}_{k} = \begin{pmatrix} 1 & 0 & \cdots & 0 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & -\mu_{k+1} & 1 & \cdots & 0 \\ \vdots & \vdots & & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & -\mu_{n} & 0 & \cdots & 1 \end{pmatrix},$$

and
$$\mathbf{T}_k^{-1} = \mathbf{I} + \mathbf{c}_k \mathbf{e}_k^{\top}$$
.



Any type III row transformation that is required to eliminate the elements below the k-th pivot can be performed by multiplication with \mathbf{T}_k .

$$\mathbf{T}_k \mathbf{A}_{k-1} = (\mathbf{I} - \mathbf{c}_k \mathbf{e}_k^{\top}) \mathbf{A}_{k-1} = \mathbf{A}_{k-1} - \mathbf{c}_k \mathbf{e}_k^{\top} \mathbf{A}_{k-1}$$



We obtain the decomposition by

$$\mathbf{U} = \mathbf{T}_n \cdot \mathbf{T}_{n-1} \cdot ... \cdot \mathbf{T}_1 \cdot \mathbf{A}$$

and

$$\mathbf{L} = \mathbf{T}_1^{-1} \cdot \mathbf{T}_2^{-1} \cdot \dots \cdot \mathbf{T}_n^{-1}$$

Example:

$$n = 4$$
, $\mathbf{A}\mathbf{x} = \mathbf{b}$, $\mathbf{A} = \begin{pmatrix} a_{11} & \cdots & a_{14} \\ \vdots & \ddots & \vdots \\ a_{41} & \cdots & a_{44} \end{pmatrix} = \mathbf{A}_0$

Note: Multiplying by \mathbf{T}_i changes the entries of the (n-i) lower right block. To keep the notation readable we write a_{ij} even if the entry was modified by the multiplication. The entries that change in the respective step are highlighted in color.

Step 1:

$$\mathbf{T}_{1}\mathbf{A}_{0} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ -a_{21}/a_{11} & 1 & 0 & 0 \\ -a_{31}/a_{11} & 0 & 1 & 0 \\ -a_{41}/a_{11} & 0 & 0 & 1 \end{pmatrix} \mathbf{A}_{0} = \begin{pmatrix} a_{11} & a_{12} & a_{13} & a_{14} \\ 0 & a_{22} & a_{23} & a_{24} \\ 0 & a_{32} & a_{33} & a_{34} \\ 0 & a_{42} & a_{43} & a_{44} \end{pmatrix} = \mathbf{A}_{1}$$



Step 2:

$$\mathbf{T}_{2}\mathbf{A}_{1} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & -\mathbf{a}_{32}/\mathbf{a}_{22} & 1 & 0 \\ 0 & -\mathbf{a}_{42}/\mathbf{a}_{22} & 0 & 1 \end{pmatrix} \mathbf{A}_{1} = \begin{pmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \mathbf{a}_{13} & \mathbf{a}_{14} \\ 0 & \mathbf{a}_{22} & \mathbf{a}_{23} & \mathbf{a}_{24} \\ 0 & 0 & \mathbf{a}_{33} & \mathbf{a}_{34} \\ 0 & 0 & \mathbf{a}_{43} & \mathbf{a}_{44} \end{pmatrix} = \mathbf{A}_{2}$$

Step 3:

$$\mathbf{T}_{3}\mathbf{A}_{2} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & -\mathbf{a}_{43}/\mathbf{a}_{33} & 1 \end{pmatrix} \mathbf{A}_{2} = \begin{pmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \mathbf{a}_{13} & \mathbf{a}_{14} \\ 0 & \mathbf{a}_{22} & \mathbf{a}_{23} & \mathbf{a}_{24} \\ 0 & 0 & \mathbf{a}_{33} & \mathbf{a}_{34} \\ 0 & 0 & 0 & \mathbf{a}_{44} \end{pmatrix} = \mathbf{U}$$



Effort in step *k* (in multiplications):

- $(n-k)^2$ multiplications for calculation of $\mathbf{T}_k \mathbf{A}_{k-1}$
- (n-k) multiplications for $\mathbf{T}_k^{-1} \cdot \underbrace{\mathbf{T}_{k-1}^{-1} \cdot ... \cdot \mathbf{T}_1^{-1}}_{\text{already calculated}}$

The total effort is therefore

$$\sum_{k=1}^{n} (n-k)^{2} + (n-k) = \sum_{k=1}^{n} n^{2} - 2nk + k^{2} + n - k$$

$$= n^{3} - 2n \frac{(n+1)n}{2} + \frac{n(n+1)(2n+1)}{6} + n^{2} - \frac{n(n+1)}{2}$$

$$= n \cdot \left(n^{2} - n^{2} - n + \frac{1}{3}n^{2} + \frac{1}{2}n + \frac{1}{6} + n - \frac{1}{2}n - \frac{1}{2}\right)$$

$$\approx \frac{1}{3}n^{3} + \mathcal{O}(n).$$



Problem: This only works if all $a_{kk} \neq 0$!

Pivotization: PA = LU

P is a permutation matrix which contains the required line switching transformations of the algorithm.

Switching lines to obtain a more stable algorithm.

Example:

$$\mathbf{A}_1 = \begin{pmatrix} 1 & 2 & -1 & 0 \\ 0 & 0 & 1/2 & 1 \\ 0 & 2 & -1/2 & 3/2 \\ 0 & -3 & 5/2 & 0 \end{pmatrix} \quad \mathbf{P}_2 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$\mathbf{P}_2 \mathbf{A}_1 = \begin{pmatrix} 1 & 2 & -1 & 0 \\ 0 & -3 & 5/2 & 0 \\ 0 & 2 & -1/2 & 3/2 \\ 0 & 0 & 1/2 & 1 \end{pmatrix},$$

then $T_2P_2A_1$ etc.



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Calculation in general

$$\mathbf{A}_k = \mathbf{T}_k \mathbf{P}_k \mathbf{A}_{k-1}$$

It can be shown

$$T_{k-1}P_{k-1}\cdot\ldots\cdot T_1P_1=\underbrace{T_{k-1}\cdot\ldots\cdot T_1}_{T}\cdot \underbrace{P_{k-1}\cdot\ldots\cdot P_1}_{P}$$

and thus

TPA = **U** and
$$T^{-1} = L$$
.

Note: When solving the linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$ the vector \mathbf{b} must also be permuted by \mathbf{P} .



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$$\begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ I_{21} & 1 & 0 & \cdots & 0 \\ I_{31} & I_{32} & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ I_{n1} & I_{n2} & I_{n3} & \cdots & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ \vdots \\ b_n \end{pmatrix}$$



by using forward substitution

$$y_1 = b_1$$
 and $y_k = b_k - \sum_{i=1}^{k-1} I_{ki} y_i$ for $k = 2, ..., n$.

for our example the result is

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -\frac{1}{2} & -\frac{1}{2} & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 32 \\ 16 \\ 52 \end{pmatrix} \Rightarrow \mathbf{y} = \begin{pmatrix} 32 \\ -48 \\ 44 \end{pmatrix}$$

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Since y is now known from step 2

$$\begin{pmatrix} u_{11} & \cdots & \cdots & u_{1n} \\ 0 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & u_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_n \end{pmatrix}$$

we can calculate **x** using **back substitution**:

$$x_i = \frac{1}{u_{ii}} \left(y_i - \sum_{k=i+1}^n u_{ik} x_k \right)$$
 for $i = n-1, n-2, \dots, 1$.

For our example the solution to the LES is:

$$\begin{pmatrix} 2 & 8 & 1 \\ 0 & -12 & -3 \\ 0 & 0 & 11 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 32 \\ -48 \\ 44 \end{pmatrix} \Rightarrow \mathbf{x} = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix}$$



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Effort of forward substitution:

In step k, k-1 multiplications are performed. If only multiplications are taken into consideration, the resulting effort is

$$\sum_{k=2}^{n} (k-1) = \sum_{k=1}^{n-1} k = \frac{(n-1)n}{2} = \frac{1}{2}n^2 - \frac{n}{2}$$

Effort of back substitution:

Similar to forward substitution, the required effort is

$$\frac{1}{2}n^2+\frac{n}{2}$$

PROPERTIES OF LU DECOMPOSITION

- "Interpretation" of the Gaussian elimination as matrix decomposition
- Numerically stable during pivoting
- Existence: For each regular matrix **A** there is a permutation matrix **P**, a normalized lower triangle matrix $\mathbf{L} \in \mathbb{R}^{n \times n}$ and a normalized upper triangular matrix $\mathbf{U} \in \mathbb{R}^{n \times n}$ such that

$$P \cdot A = L \cdot U$$

- Runtime behavior:
 - Decomposition of the matrix: $\frac{n^3}{3} + \mathcal{O}(n)$ multiplications.
 - Forward and back substitution: n²

