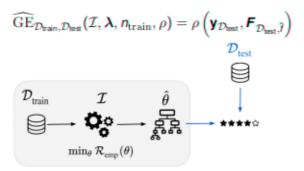
MOTIVATING EXAMPLE /2

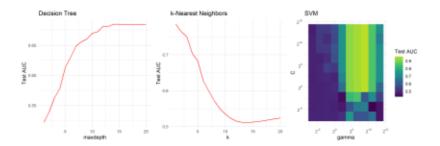
- We are actually interested in the generalization performance $\operatorname{GE}\left(\hat{f}\right)$ of the estimated model on new, previously unseen data.
- We estimate the generalization performance by evaluating the model f̂ = I(D_{train}, λ) on a test set D_{test}:





MOTIVATING EXAMPLE /3

- But many ML algorithms are sensitive w.r.t. a good setting of their hyperparameters, and generalization performance might be bad if we have chosen a suboptimal configuration.
- Consider a simulation example of 3 ML algorithms below, where
 we use the dataset mlbench. spiral and 10,000 testing points. As
 can be seen, variating hyperparameters can lead to big difference
 in model's generalization performance.

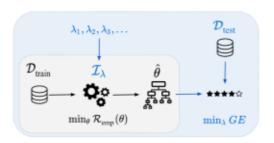




MOTIVATING EXAMPLE /4

For our example this could mean:

- Data too complex to be modeled by a tree of depth 4
- Data much simpler than we thought, a tree of depth 4 overfits
- Algorithmically try out different values for the tree depth. For each maximum depth λ, we have to train the model to completion and evaluate its performance on the test set.
 - We choose the tree depth λ that is optimal w.r.t. the generalization error of the model.





MODEL PARAMETERS VS. HYPERPARAMETERS

In contrast, hyperparameters (HPs) λ are not optimized during Incontrast, hyperparameters (HPs) \(\lambda\) are not optimized during training. They must be specified in advance, are an input of theel, i.e., training: Hyperparameters often control the complexity of a model, i.e., how flexible the model is: They can in principle influence any structural property of a model or computational part of the training process.

The process of finding the best hyperparameters is called **tuning**. The process of finding the best hyperparameters is called **tuning**.

Examples:

- Examples:

 Maximum depth of a tree
 - Maximum depth of a tree

 - k and which distance measure to use for k-NN
 - Number and maximal order of interactions to be included in a linear regression model
 - mization steps if the empirical risk minimization is
 - Number of optimization steps if the empirical risk minimization is done via gradient descent

