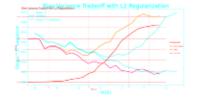
Introduction to Machine Learning

Regularization
Perspectives on Ridge Regression
(Deep-Dive)





Learning goals

- Interpretation of L2 regularization as row-augmentation
- Interpretation of L2 regularization as minimizing risk under feature noise

PERSPECTIVES ON L2 REGULARIZATION

We already saw two interpretations of L2 regularization.

• We know that it is equivalent to a constrained optimization problem:

$$\hat{\boldsymbol{\theta}}_{\text{ridge}} = \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{T} \mathbf{x}^{(i)} \right)^{2} + \lambda \|\boldsymbol{\theta}\|_{2}^{2} = (\mathbf{X}^{T} \mathbf{X} + \lambda \boldsymbol{I})^{-1} \mathbf{X}^{T} \mathbf{y}$$

For some t depending on λ this is equivalent to:

$$\hat{\boldsymbol{\theta}}_{\text{ridge}} = \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(y^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 \text{ s.t. } \|\boldsymbol{\theta}\|_2^2 \le t$$

 Bayesian interpretation of ridge regression: For additive Gaussian errors N(0, σ²) and i.i.d. normal priors θ_j ~ N(0, τ²), the resulting MAP estimate is θ̂_{ridge} with λ = σ²/2:

$$\hat{\theta}_{\mathsf{MAP}} = \underset{\boldsymbol{\theta}}{\mathsf{arg}} \max \log[p(\mathbf{y}|\mathbf{X},\boldsymbol{\theta})p(\boldsymbol{\theta})] = \underset{\boldsymbol{\theta}}{\mathsf{arg}} \min \sum_{i=1}^{n} \left(\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\mathsf{T}} \mathbf{x}^{(i)} \right)^{2} + \frac{\sigma^{2}}{\tau^{2}} \|\boldsymbol{\theta}\|_{2}^{2}$$

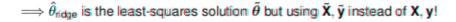


L2 AND ROW-AUGMENTATION

We can also recover the ridge estimator by performing least-squares on a **row-augmented** data set: Let $\tilde{\mathbf{X}} := \begin{pmatrix} \mathbf{X} \\ \sqrt{\lambda} \mathbf{I}_p \end{pmatrix}$ and $\tilde{\mathbf{y}} := \begin{pmatrix} \mathbf{y} \\ \mathbf{0}_p \end{pmatrix}$.

With the augmented data, the unreg. least-squares solution $\tilde{ heta}$ is:

$$\begin{split} \tilde{\boldsymbol{\theta}} &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n+p} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 \\ &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 + \sum_{j=1}^{p} \left(0 - \sqrt{\lambda} \theta_j \right)^2 \\ &= \arg\min_{\boldsymbol{\theta}} \sum_{i=1}^{n} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^T \mathbf{x}^{(i)} \right)^2 + \lambda \|\boldsymbol{\theta}\|_2^2 \end{split}$$



This is a sometimes useful "recasting" or "rewriting" for ridge.



L2 AND NOISY FEATURES

Now consider perturbed features $\tilde{\mathbf{x}}^{(i)} := \mathbf{x}^{(i)} + \delta^{(i)}$ where $\delta^{(i)} \stackrel{iid}{\sim} (\mathbf{0}, \lambda I_p)$. We assume no specific distribution. Now minimize risk with L2 loss, we define it slightly different than usual, as here our data $\mathbf{x}^{(i)}$, $\mathbf{y}^{(i)}$ are fixed, but we integrate over the random permutations δ :

$$\begin{split} \mathcal{R}(\boldsymbol{\theta}) &:= \mathbb{E}_{\boldsymbol{\delta}} \Big[\sum_{i=1}^n (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top \tilde{\mathbf{x}}^{(i)})^2 \Big] = \mathbb{E}_{\boldsymbol{\delta}} \Big[\sum_{i=1}^n (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top (\mathbf{x}^{(i)} + \boldsymbol{\delta}^{(i)}))^2 \Big] \; \Big| \; \text{expand} \\ \mathcal{R}(\boldsymbol{\theta}) &= \mathbb{E}_{\boldsymbol{\delta}} \Big[\sum_{i=1}^n ((\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top \mathbf{x}^{(i)})^2 - 2\boldsymbol{\theta}^\top \boldsymbol{\delta}^{(i)} (\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^\top \mathbf{x}^{(i)}) + \boldsymbol{\theta}^\top \boldsymbol{\delta}^{(i)} \boldsymbol{\delta}^{(i)\top} \boldsymbol{\theta}) \Big] \end{split}$$

By linearity of expectation, $\mathbb{E}_{\delta}[\delta^{(i)}] = \mathbf{0}_{\rho}$ and $\mathbb{E}_{\delta}[\delta^{(i)}\delta^{(i)\top}] = \lambda I_{\rho}$, this is

$$\mathcal{R}(\boldsymbol{\theta}) = \sum_{i=1}^{n} ((\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)})^{2} - 2\boldsymbol{\theta}^{\top} \mathbb{E}_{\boldsymbol{\delta}} [\boldsymbol{\delta}^{(i)}] (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)}) + \boldsymbol{\theta}^{\top} \mathbb{E}_{\boldsymbol{\delta}} [\boldsymbol{\delta}^{(i)} \boldsymbol{\delta}^{(i)\top}] \boldsymbol{\theta})$$
$$= \sum_{i=1}^{n} (\mathbf{y}^{(i)} - \boldsymbol{\theta}^{\top} \mathbf{x}^{(i)})^{2} + \lambda ||\boldsymbol{\theta}||_{2}^{2}$$

⇒ Ridge regression on unperturbed features **x**⁽ⁱ⁾ turns out to be the same as minimizing squared loss averaged over feature noise distribution!

