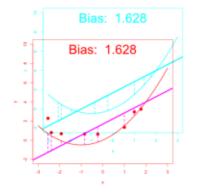
Introduction to Machine Learning

Advanced Risk Minimizationn (Deep-Dive)
Bias-Variance Decomposition (Deep-Dive)





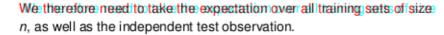
Learning goals

- Understand how to decompose Learning goals
 - Understand how to decompose the generalization error of a learner into
 - Bias of the fearnerner
 - Variance of the learner a
 - Inherent noise in the data

BIAS-VARIANCE DECOMPOSITION

Let us take a closer look at the generalization error of a learning algorithm \mathcal{I}_L . This is the expected error of an induced model $\hat{f}_{\mathcal{D}_n}$, on training sets of size n, when applied to a fresh, random test observation.

$$GE_{n}\left(\mathcal{I}_{L}\right) = \mathbb{E}_{\mathcal{D}_{n} \sim \mathbb{P}_{xy}^{n}, (\mathbf{x}, y) \sim \mathbb{P}_{xy}}\left(L\left(y, \hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)\right) = \mathbb{E}_{\mathcal{D}_{n}, xy}\left(L\left(y, \hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)\right)$$



We assume that the data is generated by

$$y = f_{true}(\mathbf{x}) + \epsilon$$
,

with zero-mean homoskedastic error $e \sim (0, \sigma^2)$ independent of \mathbf{x} .



BIAS-VARIANCE DECOMPOSITION /2

By plugging in the L2 loss $L(y, f(\mathbf{x})) = (y - f(\mathbf{x}))^2$ we get

$$GE_{n}(\mathcal{I}_{L}) = \mathbb{E}_{\mathcal{D}_{n},xy}\left(L\left(y,\hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)\right) = \mathbb{E}_{\mathcal{D}_{n},xy}\left(\left(y-\hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)^{2}\right)$$

$$\stackrel{\text{LIE}}{=} \mathbb{E}_{xy}\left[\underbrace{\mathbb{E}_{\mathcal{D}_{n}}\left(\left(y-\hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)^{2} \mid \mathbf{x},y\right)}_{(*)}\right]$$



Let us consider the error (*) conditioned on one fixed test observation (\mathbf{x}, y) first. (We omit the $|\mathbf{x}, y|$ for better readability for now.)

$$(*) = \mathbb{E}_{\mathcal{D}_{B}}\left(\left(y - \hat{t}_{\mathcal{D}_{B}}(\mathbf{x})\right)^{2}\right)$$

$$= \underbrace{\mathbb{E}_{\mathcal{D}_{B}}\left(y^{2}\right)}_{=y^{2}} + \underbrace{\mathbb{E}_{\mathcal{D}_{B}}\left(\hat{t}_{\mathcal{D}_{B}}(\mathbf{x})^{2}\right)}_{(1)} - 2\underbrace{\mathbb{E}_{\mathcal{D}_{B}}\left(y\hat{t}_{\mathcal{D}_{B}}(\mathbf{x})\right)}_{(2)}$$

by using the linearity of the expectation.

BIAS-VARIANCE DECOMPOSITION /3

$$(*) = \mathbb{E}_{\mathcal{D}_{\mathcal{B}}}\left(\left(y - \hat{f}_{\mathcal{D}_{\mathcal{B}}}(\mathbf{x})\right)^{2}\right) = y^{2} + \underbrace{\mathbb{E}_{\mathcal{D}_{\mathcal{B}}}\left(\hat{f}_{\mathcal{D}_{\mathcal{B}}}(\mathbf{x})^{2}\right)}_{(1)} - 2\underbrace{\mathbb{E}_{\mathcal{D}_{\mathcal{B}}}\left(y\hat{f}_{\mathcal{D}_{\mathcal{B}}}(\mathbf{x})\right)}_{(2)} =$$

Using that $\mathbb{E}(z^2) = \text{Var}(z) + \mathbb{E}^2(z)$, we see that

$$= y^2 + \mathsf{Var}_{\mathcal{D}_n}\left(\hat{f}_{\mathcal{D}_n}(\boldsymbol{x})\right) + \mathbb{E}^2_{\mathcal{D}_n}\left(\hat{f}_{\mathcal{D}_n}(\boldsymbol{x})\right) - 2y\mathbb{E}_{\mathcal{D}_n}\left(\hat{f}_{\mathcal{D}_n}(\boldsymbol{x})\right)$$

Plug in the definition of y

$$=\mathit{f}_{\mathtt{TUD}}(\mathbf{x})^{2}+2\epsilon\mathit{f}_{\mathtt{TUD}}(\mathbf{x})+\epsilon^{2}+\mathsf{Var}_{\mathcal{D}_{B}}\left(\hat{\mathit{f}}_{\mathcal{D}_{B}}(\mathbf{x})\right)+\mathbb{E}_{\mathcal{D}_{B}}^{2}\left(\hat{\mathit{f}}_{\mathcal{D}_{B}}(\mathbf{x})\right)-2\left(\mathit{f}_{\mathtt{TUD}}(\mathbf{x})+\epsilon\right)\mathbb{E}_{\mathcal{D}_{B}}\left(\hat{\mathit{f}}_{\mathcal{D}_{B}}(\mathbf{x})\right)$$

Reorder terms and use the binomial formula

$$=\epsilon^2 + \mathsf{Var}_{\mathcal{D}_{\mathcal{B}}}\left(\hat{\mathit{f}}_{\mathcal{D}_{\mathcal{B}}}(\mathbf{x})\right) + \left(\mathit{f}_{\mathtt{Bue}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_{\mathcal{B}}}\left(\hat{\mathit{f}}_{\mathcal{D}_{\mathcal{B}}}(\mathbf{x})\right)\right)^2 + 2\epsilon\left(\mathit{f}_{\mathtt{Bue}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_{\mathcal{B}}}\left(\hat{\mathit{f}}_{\mathcal{D}_{\mathcal{B}}}(\mathbf{x})\right)\right)$$



BIAS-VARIANCE DECOMPOSITION /4

$$(*) = \epsilon^2 + \mathsf{Var}_{\mathcal{D}_n}\left(\hat{\mathit{f}}_{\mathcal{D}_n}(\mathbf{x})\right) + \left(\mathit{f}_{\mathsf{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}\left(\hat{\mathit{f}}_{\mathcal{D}_n}(\mathbf{x})\right)\right)^2 + 2\epsilon\left(\mathit{f}_{\mathsf{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}\left(\hat{\mathit{f}}_{\mathcal{D}_n}(\mathbf{x})\right)\right)$$

Let us come back to the generalization error by taking the expectation over all fresh test observations $(\mathbf{x}, y) \sim \mathbb{P}_{xy}$:



$$\begin{aligned} \textit{GE}_{n}\left(\mathcal{I}_{L}\right) &= \underbrace{\sigma^{2}}_{\text{Variance of the data}} + \mathbb{E}_{xy} \underbrace{\left[\text{Var}_{\mathcal{D}_{n}}\left(\hat{t}_{\mathcal{D}_{n}}(\mathbf{x}) \mid \mathbf{x}, y\right) \right]}_{\text{Variance of learner at } (\mathbf{x}, y)} \\ &+ \mathbb{E}_{xy} \underbrace{\left[\left(\left(f_{\text{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_{n}}\left(\hat{t}_{\mathcal{D}_{n}}(\mathbf{x})\right)\right)^{2} \mid \mathbf{x}, y\right) \right]}_{\text{Squared bias of learner at } (\mathbf{x}, y)} + \underbrace{0}_{\text{As } \epsilon \text{ is zero-mean and independent}} \end{aligned}$$