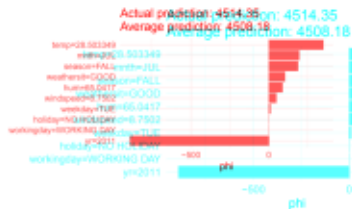


Interpretable Machine Learning

Shapley Values for Local Explanations

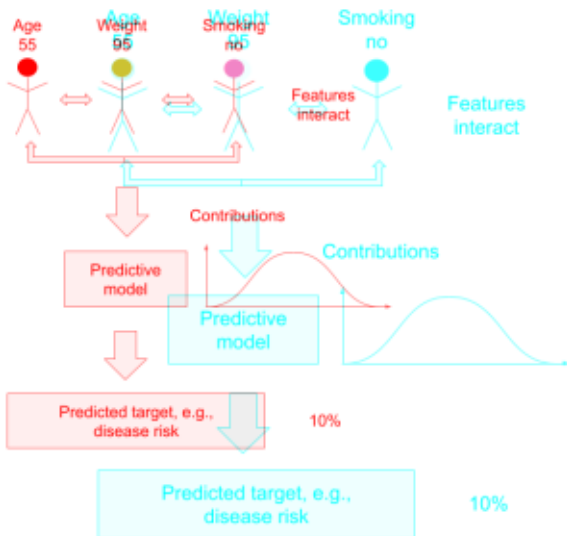


Learning goals

Learning goals

- See model predictions as a cooperative game
 - See model predictions as a cooperative game
- Transfer the Shapley value concept from game theory to machine learning
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FROM GAME THEORY TO MACHINE LEARNING



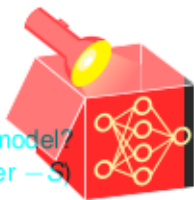
FROM GAME THEORY TO MACHINE LEARNING

- Game: Make prediction of $\hat{y}(x_1, x_2, \dots, x_p)$ for a single observation x

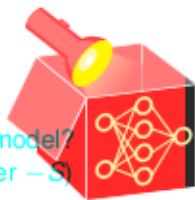


FROM GAME THEORY TO MACHINE LEARNING

- Game: Make prediction of $\hat{y}(x_1, x_2, \dots, x_p)$ for a single observation \mathbf{x}
- Players: Features $x_j, j \in \{1, \dots, p\}$, which cooperate to produce a prediction
~> How can we make a prediction with a subset of features without changing the model?
model function: $\hat{f}_S(\mathbf{x}_S) := \int_{\mathcal{X}_{-S}} \hat{f}(\mathbf{x}_S, \mathbf{x}_{-S}) d\mathbb{P}_{\mathcal{X}_{-S}}$ ("removing" by marginalizing over $-S$)
~> PD function: $\hat{f}_S(\mathbf{x}_S) := \int_{\mathcal{X}_{-S}} \hat{f}(\mathbf{x}_S, \mathbf{x}_{-S}) d\mathbb{P}_{\mathcal{X}_{-S}}$ ("removing" by marginalizing over $-S$)



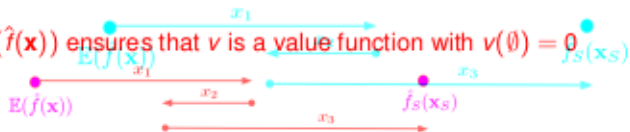
FROM GAME THEORY TO MACHINE LEARNING



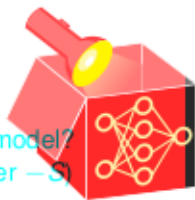
- Game: Make prediction of $\hat{f}(x_1, x_2, x_3, \dots, x_p)$ for a single observation \mathbf{x}
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- Value function / payout of coalition $S \subseteq P$ for observation \mathbf{x} :
 - ~> PD function: $\hat{f}_S(\mathbf{x}_S) := \int_{\mathcal{X}_{-S}} \hat{f}(\mathbf{x}_S, \mathbf{X}_{-S}) d\mathbb{P}_{\mathcal{X}_{-S}}$ ("removing" by marginalizing over $-S$)
- Value function / payout of coalition $S \subseteq P$ for observation \mathbf{x} where $\hat{f}_S : \mathcal{X}_S \mapsto \mathcal{Y}$

~> subtraction $v(S, \mathbf{x}) = \hat{f}_S(\mathbf{x}_S) - \mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$, where \hat{f}_S is a PD function with $v(\emptyset) = 0$

~> subtraction of $\mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$ ensures that v is a value function with $v(\emptyset) = 0$

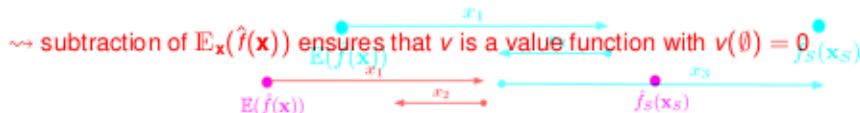


FROM GAME THEORY TO MACHINE LEARNING



- Game: Make prediction of $\hat{f}(x_1, x_2, x_3, \dots, x_p)$ for a single observation \mathbf{x}
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~> subtraction $v(S) = \hat{f}_S(\mathbf{x}_S) - \mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$, where \hat{f}_S is a value function with $v(\emptyset) = 0$



- Marginal contribution: $v(S \cup \{j\}) - v(S) = \hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) - \hat{f}_S(\mathbf{x}_S)$
- Marginal contribution: $v(S \cup \{j\}) - v(S) = \hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) - \hat{f}_S(\mathbf{x}_S)$
 - ~> $\mathbb{E}_{\mathbf{x}}(\hat{f}(\mathbf{x}))$ cancels out due to the subtraction of value functions



Shapley value ϕ_j of feature j for observation \mathbf{x} via **order definition**:

$$\phi_j(\mathbf{x}) = \frac{1}{|P|!} \sum_{\tau \in \Pi} \underbrace{\hat{f}_{S_{\tau} \cup \{j\}}(\mathbf{x}_{S_{\tau} \cup \{j\}}) - \hat{f}_{S_{\tau}}(\mathbf{x}_{S_{\tau}})}_{\text{marginal contribution of feature } j}$$

- Interpretation: Feature x_j contributed ϕ_j to difference between $\hat{f}(\mathbf{x})$ and average prediction
- Note: Marginal contributions and Shapley values can be negative
- \rightsquigarrow Note: Marginal contributions and Shapley values can be negative
- For exact computation of $\phi_j(\mathbf{x})$, the PD function $f_S(\mathbf{x}_S) = \frac{1}{n} \sum_{i=1}^n \hat{f}(\mathbf{x}_S, \mathbf{x}_{-S}^{(i)})$ for any set of features S can be used which yields

$$\phi_j(\mathbf{x}) = \frac{\phi_j(\mathbf{x})}{|P|! \cdot n} \sum_{\tau \in \Pi} \sum_{i=1}^n \hat{f}^{(i)}(\mathbf{x}_{S_{\tau} \cup \{j\}}, \mathbf{x}_{-(S_{\tau} \cup \{j\})}^{(i)}) - \hat{f}(\mathbf{x}_{S_{\tau}}, \mathbf{x}_{-S_{\tau}}^{(i)})$$

- \rightsquigarrow Note: \hat{f}_S marginalizes over all other features $-S$ using all observations $i = 1, \dots, n$
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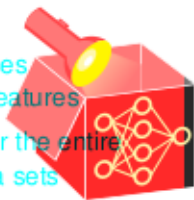
ESTIMATION: A PRACTICAL PROBLEM

- Exact Shapley value computation is problematic for high-dimensional feature spaces
- For 10 features, there are already $|P| = 10! \approx 3.6$ million possible orders of features
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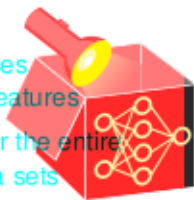
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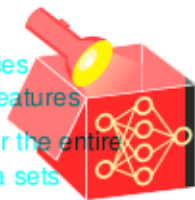
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 - ↳ The higher M , the closer to the exact Shapley values, but the more costly the computation
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APPROXIMATION ALGORITHM Strombel et al. (2014)

Estimation of α_j for observation x of model \hat{f} fitted on data D using sample size M :

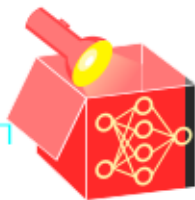
1 For $m=1, \dots, M$ do do:



Estimation of α_j for observation x of model \hat{f} fitted on data D using sample size M :

1 For $m=1, \dots, M$ do do:

1 Select random order / perm. of feature indices $\tau = (\tau^{(1)}, \dots, \tau^{(p)}) \in \Pi, \tau^{(p)} \in \Pi$



Estimation of α_j for observation x of model f fitted on data D using sample size M :

1 For $m=1, \dots, M$ do:

- 1 Select random order / perm. of feature indices $\tau = (\tau^{(1)}, \dots, \tau^{(p)}) \in \Pi$
- 2 Determine coalition $S_m = S_j^\tau$, i.e. the set of feat. before feat. j in order τ



Estimation of α_j for observation x of model \hat{f} fitted on data \mathcal{D} using sample size M :

1 For $m=1, \dots, M$ do do:

- 1 Select random order / perm. of feature indices $\tau = (\tau^{(1)}, \dots, \tau^{(p)}) \in \Pi$
- 2 Determine coalition $S_m = S_j^\tau$, i.e., the set of feat. before feat. j in order τ
- 3 Select random data point $z^{(m)} \in \mathcal{D}$



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Estimation of α_j for observation \mathbf{x} of model f fitted on data \mathcal{D} using sample size M :



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3 Select random data point $\mathbf{z}^{(m)} \in \mathcal{D}$

4 Construct two artificial obs. by replacing feature values from \mathbf{x} with $\mathbf{z}^{(m)}$:

• $\mathbf{x}_{-j}^{(m)} = (\underbrace{X_{\tau^{(1)}}, \dots, X_{\tau^{(|S_m|-1)}}}_{\mathbf{x}_{S_m \cup \{j\}}}, \underbrace{X_j, Z_{\tau^{(|S_m|+1)}}, \dots, Z_{\tau^{(p)}}}_{\mathbf{z}_{- \{S_m \cup \{j\}\}^{(m)}}})$ takes features $S_m \cup \{j\}$ from \mathbf{x}



Estimation of \hat{c}_j for observation \mathbf{x} of model \hat{f} fitted on data \mathcal{D} using sample size M :

1 For $m=1, \dots, M$ do do:

1 Select random order τ perm. of feature indices $\tau = (\tau^{(1)}, \dots, \tau^{(p)}) \in \Pi$

2 Determine coalition $S_m = S_j^\tau$, i.e., the set of feat. before feat. j in order τ

3 Select random data point $\mathbf{z}^{(m)} \in \mathcal{D}$

4 Construct two artificial obs. by replacing feature values from \mathbf{x} with $\mathbf{z}^{(m)}$:

• $\mathbf{x}_{+j}^{(m)} = \underbrace{(X_{\tau^{(1)}}^{(1)}, \dots, X_{\tau^{(|S_m|-1)}}^{(|S_m|-1)}, X_j, Z_{\tau^{(|S_m|+1)}}^{(m)}, \dots, Z_{\tau^{(p)}}^{(m)})}_{\mathbf{x}_{S_m \cup \{j\}}^{(m)}} \text{ takes features } S_m \cup \{j\} \text{ from } \mathbf{x}$
 $\underbrace{\hspace{10em}}_{\mathbf{z}_{-S_m \cup \{j\}}^{(m)}}$

$S_m \cup \{j\}$ from \mathbf{x}

• $\mathbf{x}_{-j}^{(m)} = \underbrace{(X_{\tau^{(1)}}^{(1)}, \dots, X_{\tau^{(|S_m|-1)}}^{(|S_m|-1)}, Z_j^{(m)}, Z_{\tau^{(|S_m|+1)}}^{(m)}, \dots, Z_{\tau^{(p)}}^{(m)})}_{\mathbf{x}_{S_m}^{(m)}} \text{ takes features } S_m \text{ from } \mathbf{x}$
 $\underbrace{\hspace{10em}}_{\mathbf{z}_{-S_m}^{(m)}}$

S_m from \mathbf{x}



Estimation of ϕ_j for observation \mathbf{x} of model \hat{f} fitted on data \mathcal{D} using sample size M :

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- 1 Select random order / perm. of feature indices $\tau = (\tau^{(1)}, \dots, \tau^{(p)}) \in \Pi$
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- $\mathbf{x}_{-j}^{(m)} = (\underbrace{X_{\tau^{(1)}}, \dots, X_{\tau^{(|S_m|-1)}}}_{\mathbf{x}_{S_m}}, \underbrace{Z_j, Z_{\tau^{(|S_m|+1)}}, \dots, Z_{\tau^{(p)}}}_{\mathbf{z}_{-S_m}^{(m)}})$ takes features S_m from \mathbf{x}

- 5 Compute difference $\phi_j^m = \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)})$
- 6 Compute difference $\phi_j^m = \hat{f}(\mathbf{x}_{+j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)})$
 - $\rightsquigarrow \hat{f}_{S_m}(\mathbf{x}_{S_m})$ is approximated by $\hat{f}(\mathbf{x}_{-j}^{(m)})$ and $\hat{f}_{S_m \cup \{j\}}(\mathbf{x}_{S_m \cup \{j\}})$ by $\hat{f}(\mathbf{x}_{+j}^{(m)})$ over M iters
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Estimation of ϕ_j for observation \mathbf{x} of model \hat{f} fitted on data \mathcal{D} using sample size M :

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• $\mathbf{x}_{-j}^{(m)} = \underbrace{(X_{\tau^{(1)}}^{(1)}, \dots, X_{\tau^{(|S_m|-1)}}^{(1)}, Z_j^{(m)}, Z_{\tau^{(|S_m|+1)}}^{(m)}, \dots, Z_{\tau^{(p)}}^{(m)})}_{\mathbf{x}_{S_m}^{(m)}}$ takes features S_m from \mathbf{x}

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3 Compute Shapley value $\phi_j = \frac{1}{M} \sum_{m=1}^M \phi_j^m$

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SHAPLEY VALUE APPROXIMATION - ILLUSTRATION

Definition

\mathbf{x} : obs. of interest
 \mathbf{x} with feature values in S_m (other are replaced)
 \mathbf{x} with feature values in $S_m \cup \{j\}$
 \mathbf{x} with feature values in $S_m \cup \{j\}$

$$\phi_j(\mathbf{x}) = \frac{1}{M} \sum_{m=1}^M \left[\hat{f}(\mathbf{x}_{-j}^{(m)}) - \hat{f}(\mathbf{x}_{-j}^{(m)}) \right]$$



	Temperature	Humidity	Windspeed	Year
\mathbf{x}	10.66	56	11	2012
\mathbf{x}_{+j}	10.66	56	random: 11	2012
\mathbf{x}_{-j}	10.66	56	random: 11	random: 2012

} j } j

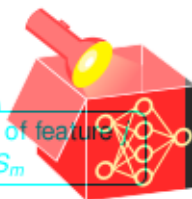
SHAPLEY VALUE APPROXIMATION - ILLUSTRATION

Definition

Contribution of feature j to coalition S_m

$$\phi_j(x) = \frac{1}{M} \sum_{m=1}^M \left[\underbrace{\hat{f}(x_{-j}^{(m)})}_{:= \Delta(j, S_m)} - \underbrace{\hat{f}(x_{-j}^{(m)})}_{:= \Delta(j, S_m)} - \hat{f}(x_{-j}^{(m)}) \right]$$

Contribution of feature j to coalition S_m



- $\Delta(j, S_m) = \hat{f}(x_{-j}^{(m)}) - \hat{f}(x_{-j}^{(m)})$ is the marginal contribution of feature j to coalition S_m
- Here: Feature *year* contributes +700 bike rentals if it joins coalition $S_m = \{\text{temp, hum}\}$
- Here: Feature *year* contributes +700 bike rentals if it joins coalition



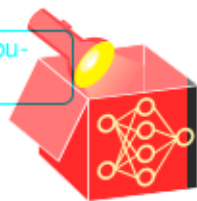
SHAPLEY VALUE APPROXIMATION - ILLUSTRATION

Definition

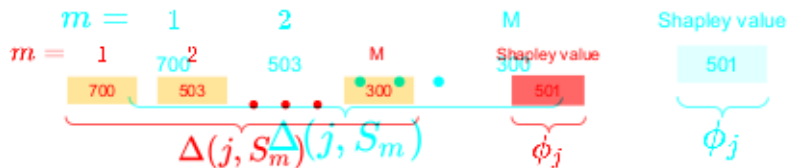
$$\phi_j(x) = \frac{1}{M} \sum_{m=1}^M \left[\hat{f}(x_{-j}^{(m)}) - \hat{f}(x_{-j}^{(m)}) \right]$$

average the contributions of feature j

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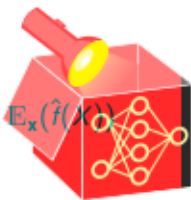
- Compute marginal contribution of feature j towards the prediction across all randomly drawn feature coalitions S_1, \dots, S_m
- Average all M marginal contributions of feature j
- Average all M marginal contributions of feature j
- Shapley value ϕ_j is the payout of feature j , i.e., how much feature j contributed to the overall prediction in bicycle counts of a specific observation x
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REVISITED: AXIOMS FOR FAIR ATTRIBUTIONS

We take the general axioms for Shapley Values and apply it to prediction functions:

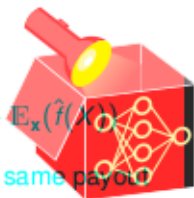
- **Efficiency:** Shapley values add up to the (centered) prediction function: $\sum_{j=1}^p \phi_j = \hat{f}(\mathbf{x}) - \mathbb{E}_{\mathbf{x}}(\hat{f}(X))$



REVISITED: AXIOMS FOR FAIR ATTRIBUTIONS

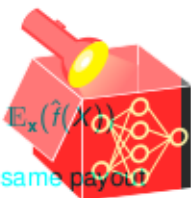
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↪ interaction effects between features are fairly divided
 $\hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) = \hat{f}_{S \cup \{k\}}(\mathbf{x}_{S \cup \{k\}})$ for all $S \subseteq P \setminus \{j, k\}$ then $\phi_j = \phi_k$



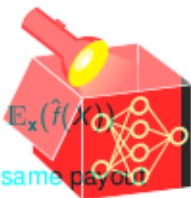
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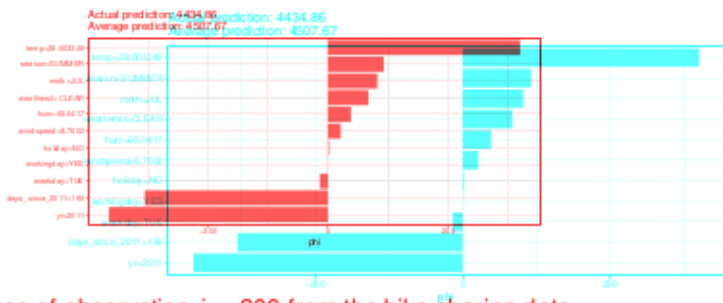
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↪ interaction effects between features are fairly divided
- **Dummy / Null Player:** Shapley value of a feature that does not influence the prediction is zero
↪ if a feature was not selected by the model (e.g., tree or LASSO), its Shapley value is zero
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 $\hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) = \hat{f}_S(\mathbf{x}_S)$ for all $S \subseteq P$ then $\phi_j = 0$

REVISITED: AXIOMS FOR FAIR ATTRIBUTIONS



We take the general axioms for Shapley Values and apply it to predictions:

- Efficiency:** Shapley values add up to the (centered) prediction: $\sum_{j=1}^p \phi_j = \hat{f}(\mathbf{x}) - \mathbb{E}_{\mathbf{x}}(\hat{f}(X))$
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- Dummy / Null Player:** Shapley value of a feature that does not influence the prediction is zero \rightsquigarrow if a feature was not selected by the model (e.g., tree or LASSO), its Shapley value is zero
- Additivity:** For a prediction with combined payouts, the payout is the sum of payouts:
 $\hat{f}_{S \cup \{j\}}(\mathbf{x}_{S \cup \{j\}}) = \hat{f}_S(\mathbf{x}_S) + \phi_j$ for all $S \subseteq P$ then $\phi_j = 0$
- Additivity:** For a prediction with combined payouts, the payout is the sum of payouts: $\phi_j(v_1) + \phi_j(v_2) \rightsquigarrow$ Shapley values for model ensembles can be combined

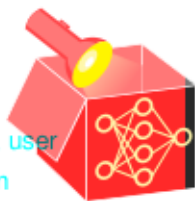


- Shapley values of observation $i = 200$ from the bike sharing data
- Difference between model prediction of this observation and the average prediction of the data is fairly distributed among the features (i.e., $4434 - 4507 \approx -73$)
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ADVANTAGES AND DISADVANTAGES

Advantages:

- **Solid theoretical foundation** in game theory
- Prediction is **fairly distributed** among the feature values → easy to interpret for a user
 - **Contrastive explanations** that compare the prediction with the average prediction
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Disadvantages:

- Without sampling, Shapley values need a lot of computing time to inspect all possible coalitions

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