It is common but by no means necessary to consider GPs with a zero-mean function

$$m(\mathbf{x}) \equiv 0$$

Note that this is not necessarily a drastic limitation, since the mean of the posterior process is not confined to be zero

Posterior process after 4 observations
$$f_*|\mathbf{X}_*,\mathbf{X},f_*\rangle \mathcal{N}\big(\mathbf{K}_*^T\mathbf{K}^{-1}f,\mathbf{K}_{**}-\mathbf{K}_*^T\mathbf{K}^{-1}\mathbf{K}_*\big).$$
 Learning goals

- Yet there are several reasons why one might wish to explicitly model a mean function, including interpretability, convenience of expressing prior informations, ...
- When assuming a non-zero mean GP prior $\mathcal{GP}(m(\mathbf{x}), k(\mathbf{x}, \mathbf{x}'))$ with mean $m(\mathbf{x})$, the predictive mean becomes

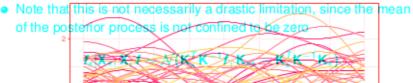
$$m(\mathbf{X}_*) + \mathbf{K}_* \mathbf{K}_y^{-1} (\mathbf{y} - m(\mathbf{X}))$$

while the predictive variance remains unchanged.



 Gaussian processes with non-zero mean Gaussian process priors are also called Gaussian processes with trend.





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- When assuming a non-zero mean Prior P (m(x), k (x, x))
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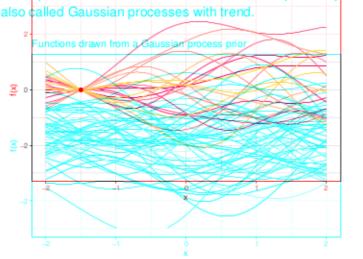
$$m(\overline{\mathbf{X}}_{*}^{1}) + \mathbf{K}_{*}\mathbf{K}_{y}^{-10}(y - m(\mathbf{X}))$$

while the predictive variance remains unchanged.

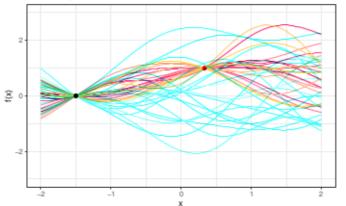


 Gaussian Posterior process after 1 observation
 Gaussian process priors are also called Gaussian processes with trend.

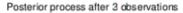


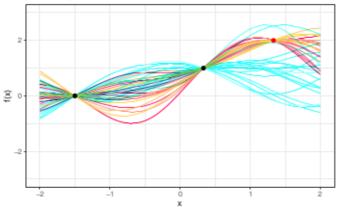






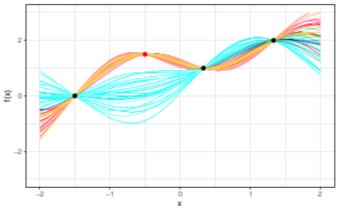














- In practice it can often be difficult to specify a fixed mean function
- In many cases it may be more convenient to specify a few fixed basis functions, whose coefficients, β, are to be inferred from the data
- Consider

$$g(\mathbf{x}) \equiv b(\mathbf{x})^{\top} \boldsymbol{\beta} + f(\mathbf{x}), \text{ where } f(\mathbf{x}) \sim \mathcal{GP}(0, k(\mathbf{x}, \tilde{\mathbf{x}}))$$

- This formulation expresses that the data is close to a global linear model with the residuals being modelled by a GP.
- For the estimation of $g(\mathbf{x})$ please refer to Rasmussen, Gaussian Processes for Machine Learning, 2006



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